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# H8/38076R

## Master-Slave Communication Using I<sup>2</sup>C Clock-Synchronous Serial Format

### Introduction

In this example the I<sup>2</sup>C2 (Inter IC Bus Interface 2) module of the H8/38076R is used for master-slave communication in I<sup>2</sup>C clock-synchronous serial format.

### Target Device

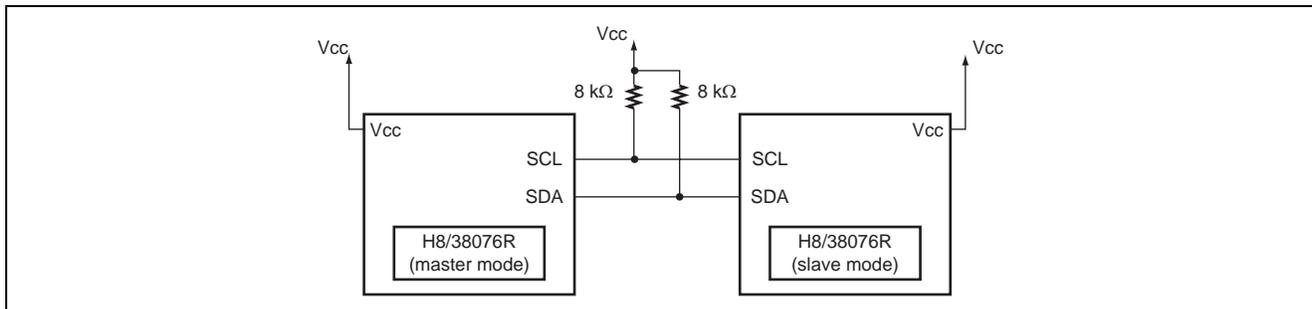
H8/38076R

### Contents

1. Specifications .....	2
2. Description of Functions .....	3
3. Sequence Diagram .....	6
4. Principles of Operation.....	7
5. Description of Software (Master) .....	8
6. Description of Software (Slave) .....	17

## 1. Specifications

- The I<sup>2</sup>C clock-synchronous serial format of the H8/38076R is used for communication between microcomputers as shown in figure 1.
- In this sample task 4 bytes of data are transmitted from an H8/38076R operating in the master mode and received by an H8/38076R operating in the slave mode.
- The slave H8/38076R then transmits the receive data to the master H8/38076R.
- The transfer clock frequency is 100 kHz.



**Figure 1 Connection Diagram for Master-Slave Communication Using the I<sup>2</sup>C Clock-Synchronous Serial Format**

## 2. Description of Functions

### 2.1 Functions Used

In this sample task the I<sup>2</sup>C clock-synchronous serial format is used to implement master-slave communication. A block diagram of the I<sup>2</sup>C bus interface 2 is shown in figure 2, and its functions are described below.

#### 1. I<sup>2</sup>C Bus Interface 2 Functions

The I<sup>2</sup>C bus interface 2 conforms to and provides a subset of the Philips I<sup>2</sup>C bus (Inter IC Bus) interface functions.

- I<sup>2</sup>C bus control register 1 (ICCR1)  
ICCR1 enables or disables the I<sup>2</sup>C bus interface 2, controls transmission and reception, and selects the master mode or the slave mode, transmission or reception, and the transfer clock frequency in the master mode. In this sample task the transfer clock frequency is set to 100 kHz.
- I<sup>2</sup>C bus control register 2 (ICCR2)  
ICCR2 manipulates the SDA pin, monitors the SCL pin state, and controls resets of the control block of the I<sup>2</sup>C bus interface 2.
- I<sup>2</sup>C bus mode register (ICMR)  
ICMR selects whether the MSB or LSB is transferred first and selects the transfer bit count. Note that BC (bit counter) must not be overwritten when using the clock-synchronous serial format.
- I<sup>2</sup>C bus status register (ICSR)  
ICSR confirms interrupt request flags and status.
- I<sup>2</sup>C bus interrupt enable register (ICIER)  
ICIER enables interrupt sources.
- I<sup>2</sup>C bus transmit data register (ICDRT)  
ICDRT is an 8-bit readable/writable register that stores transmit data. When ICDRT detects space in the shift register (ICDRS) it transfers the transmit data which was written to ICDRT to ICDRS and starts transmitting data. Continuous transmission is possible if the next transmit data is written to ICDRT while data transfer to ICDRS is in progress. If the MLS bit of ICMR is set to 1, MSB/LSB inverted data is read after the data is written to ICDRT.
- I<sup>2</sup>C bus receive data register (ICDRR)  
ICDRR is an 8-bit register that stores receive data. After one byte of data is received, ICDRR transfers the receive data from ICDRS to ICDRR and the next data can be received. ICDRR is a receive-only register, so the CPU cannot write to it.
- I<sup>2</sup>C bus shift register (ICDRS)  
ICDRS is a register that is used to transmit and receive data. In transmission, data is transferred from ICDRT to ICDRS and the data is sent from the SDA pin. In reception, data is transferred from ICDRS to ICDRR after one byte of data is received. This register cannot be read directly from the CPU.
- Slave address register (SAR)  
SAR selects the communication format.

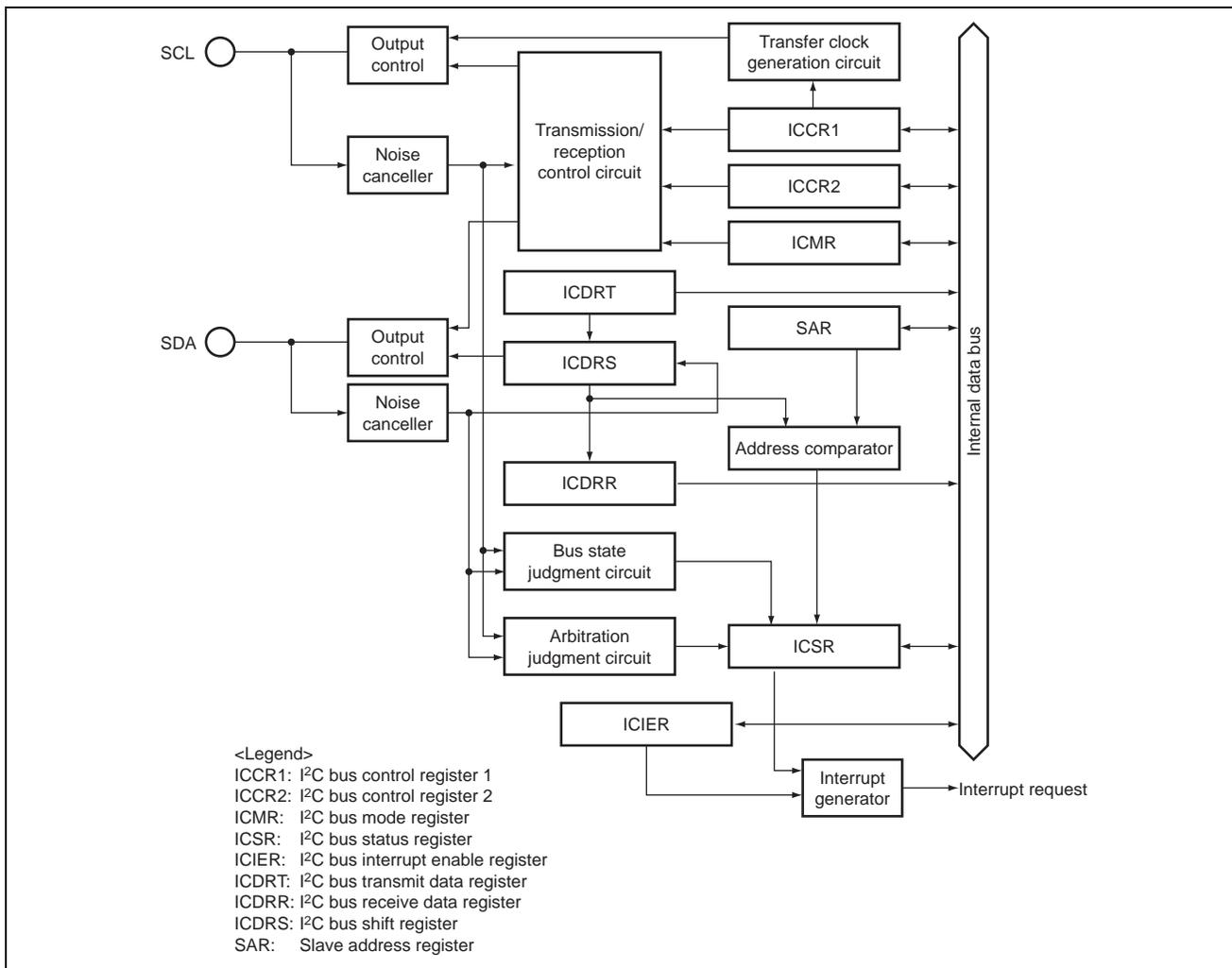


Figure 2 Block Diagram of I<sup>2</sup>C Bus Interface 2

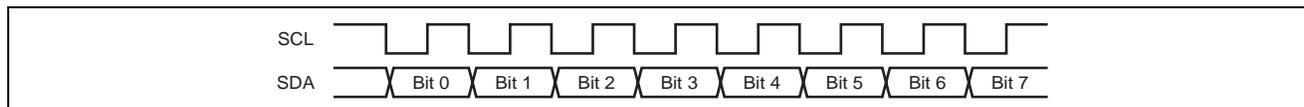
## 2.2 Assignment of Functions

Table 1 shows the assignment of functions in this sample task.

Master-slave communication using the I<sup>2</sup>C clock-synchronous serial format is implemented using functions assigned as shown in table 1. Figure 3 shows the transfer format for clock-synchronous serial communication.

**Table 1 Assignment of Functions**

Elements	Classification	Description
SCL	Pin	I <sup>2</sup> C serial clock I/O pin
SDA	Pin	I <sup>2</sup> C serial data I/O pin
ICRR1	I <sup>2</sup> C2	Starts and stops operation of I <sup>2</sup> C bus interface 2, controls transmission and reception, selects the master mode or the slave mode, selects master mode transfer clock frequency
ICRR2	I <sup>2</sup> C2	Manipulates SDA pin
ICMR	I <sup>2</sup> C2	Selects MSB or LSB first
ICSR	I <sup>2</sup> C2	Status flag indicating the I <sup>2</sup> C operation state
ICIER	I <sup>2</sup> C2	Enables various interrupt sources
ICDRT	I <sup>2</sup> C2	Register for storing transmit data
ICDRR	I <sup>2</sup> C2	Register for storing receive data
ICDRS	I <sup>2</sup> C2	Register for transmitting and receiving data
SAR	I <sup>2</sup> C2	Selects format



**Figure 3 Clock-Synchronous Serial Transfer Format**

### 3. Sequence Diagram

Figure 4 is a sequence diagram of this sample task.

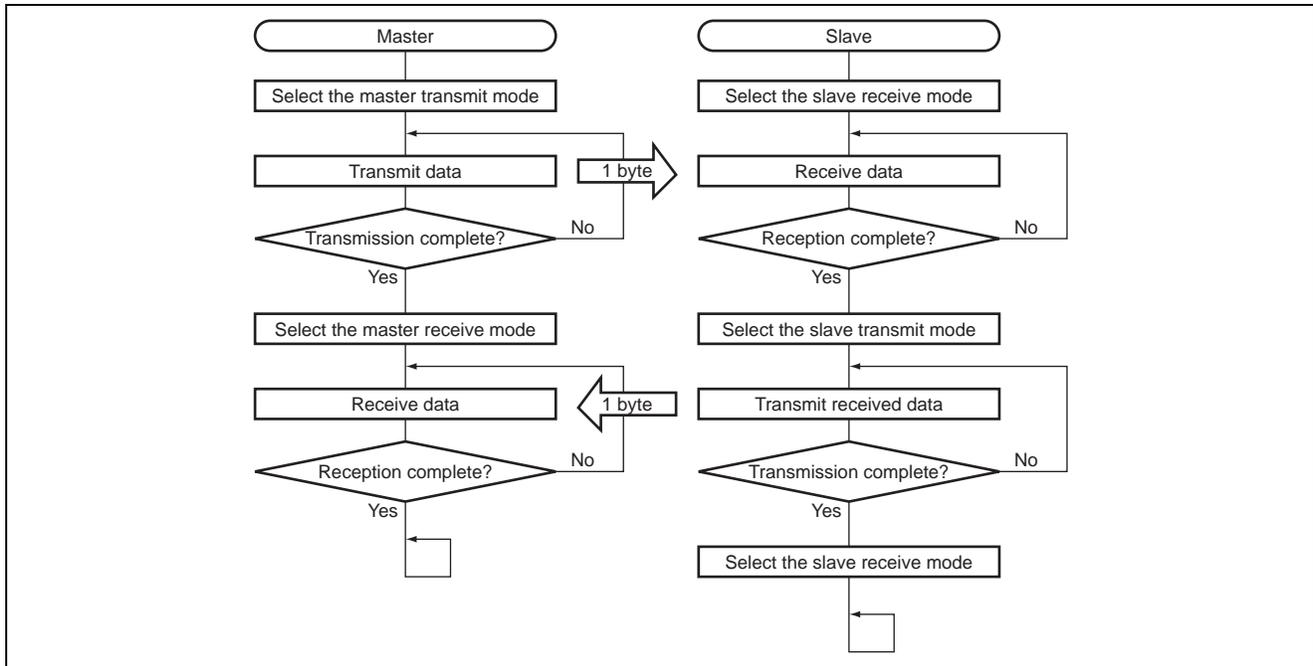


Figure 4 Sequence Diagram

## 4. Principles of Operation

### 4.1 Transmit Mode

The operation timing in the transmit mode for this sample task is illustrated in figure 5. Furthermore, details of the hardware and software processings are shown.

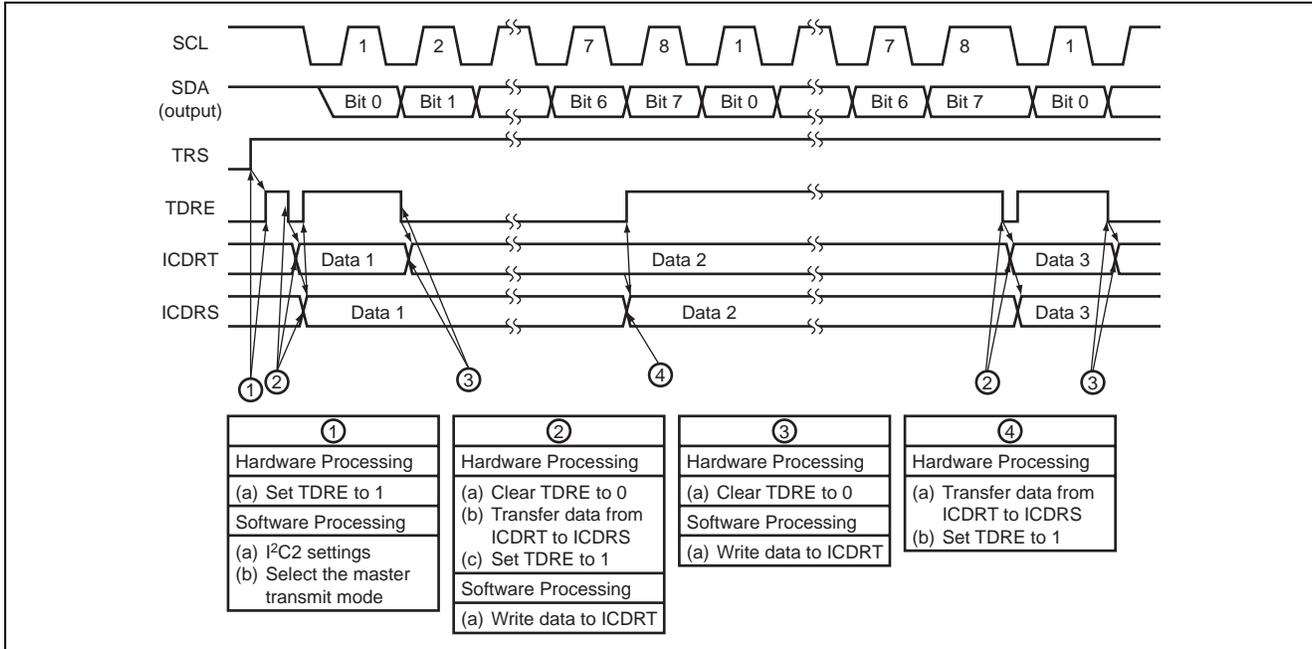


Figure 5 Transmit Mode Operation Timing

### 4.2 Receive Mode

The operation timing in the receive mode for this sample task is illustrated in figure 6. Furthermore, details of the hardware and software processings are shown.

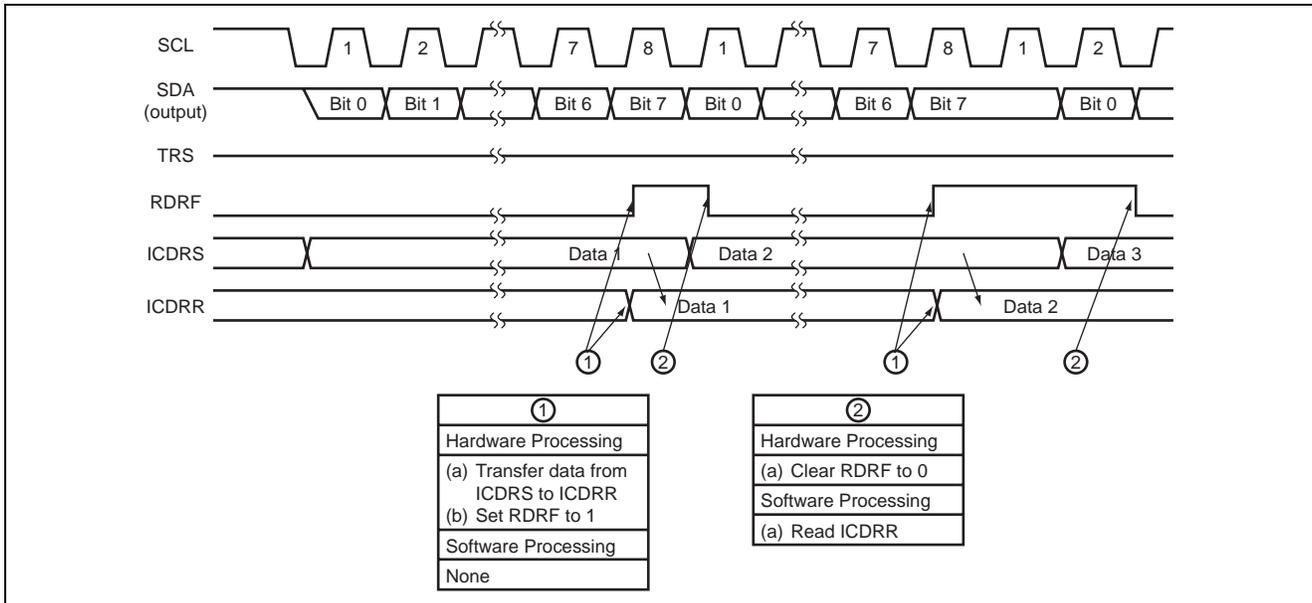


Figure 6 Receive Mode Operation Timing

## 5. Description of Software (Master)

In this sample task I<sup>2</sup>C clock-synchronous serial format initialization, master transmit, and master receive operations are performed. The functions used by the master programs are described below.

### 5.1 Functions

**Table 2 List of Master Program Functions**

Function Name	Description
main	Controls master communication
Clock_init	Initializes the I <sup>2</sup> C clock-synchronous serial format
master_trs	Master transmission
master_rcv	Master reception

### 5.2 Constants

Table 3 shows the constants used in this sample task.

**Table 3 Constants**

Label Name	Constant Value	Description	Used in
SIZE	4	Transmit/receive data size	master_trs master_rcv

### 5.3 RAM Usage

Table 4 shows the RAM used in this sample task.

**Table 4 RAM Usage**

Label Name	Description	Amount of Memory Used	Used in
m_trs[SIZE]	Buffer for storing transmit data	4 bytes	master_trs
m_rcv[SIZE]	Buffer for storing receive data	4 bytes	master_rcv

## 5.4 Modules

### 5.4.1 main() Function

1. Module Specifications
  - Controls master communication

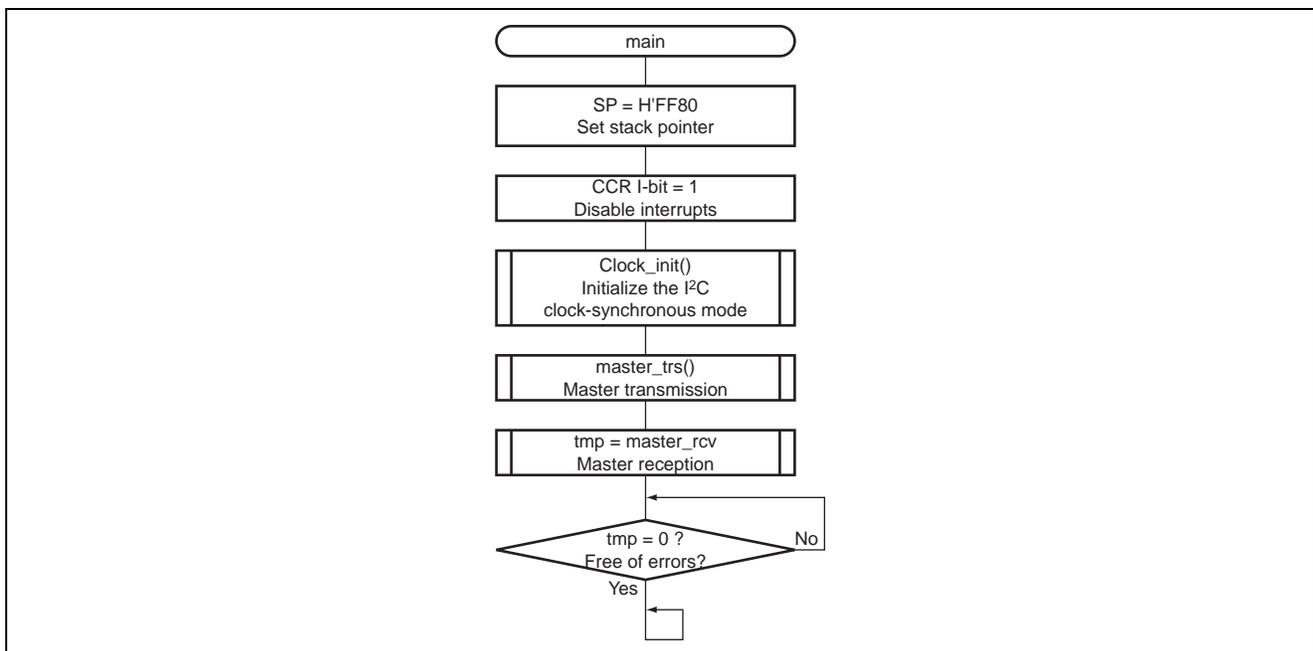
**Table 5 Module Specifications**

Item	Type	Variable	Description
Arguments	None	None	None

2. Internal Registers Used

None

3. Flowchart



### 5.4.2 Clock\_init() Function

#### 1. Module Specifications

- Initializes the I<sup>2</sup>C clock-synchronous serial format

**Table 6 Module Specifications**

Item	Type	Variable	Description
Arguments	None	None	None

#### 2. Internal Registers Used

The internal registers used in this sample task are shown below. The set values shown are those used in the sample task and differ from the initial values.

- ICCR1                      I<sup>2</sup>C bus control register 1                      Address: H'F078

Bit	Bit Name	Set Value	R/W	Description
7	ICE	1	R/W	I <sup>2</sup> C bus interface 2 enable 0: The module is halted. (SCL and SDA pins are set to the port/serial function.) 1: The module is enabled for transfer operations. (SCL and SDA pins are bus drive state.)
6	RCVD	0	R/W	Reception disable This bit enables or disables the next operation when TRS is 0 and ICDRR is read. 0: Enables next reception 1: Disables next reception
5	MST	1	R/W	Master/slave selection
4	TRS	1	R/W	Transmit/receive selection The value of the TRS bit should be changed between transfer frames. The following operation modes can be selected by the MST and TRS bits in combination. 00: Slave receive mode 01: Slave transmit mode 10: Master receive mode 11: Master transmit mode
3	CKS3	0	R/W	Transfer clock select 3 to 0
2	CKS2	1	R/W	These bits are valid only in the master mode and should be set according to the necessary transfer clock frequency. In this sample task the operating frequency $\phi$ is 10 MHz. For details on the transfer clock frequency see table 7.
1	CKS1	0	R/W	
0	CKS0	1	R/W	

**Table 7 Transfer Clock Frequency**

Bit 3	Bit 2	Bit 1	Bit 0	Transfer Clock Frequency	
CKS3	CKS2	CKS1	CKS0	Clock	$\phi = 10 \text{ MHz}$
0	1	0	1	$\phi / 100$	100 kHz

- ICCR2 I<sup>2</sup>C bus control register 2 Address: H'F079

Bit	Bit Name	Set Value	R/W	Description
5	SDAO	1	R/W	SDA output value control This bit is used with SDAOP (bit 4) for modifying the output level of SDA. This bit should not be manipulated when a transfer is in progress. <ul style="list-style-type: none"> <li>• When 0 is read, SDA pin outputs a low level</li> <li>• When 0 is written, SDA pin changes to low level output</li> <li>• When 1 is read, SDA pin outputs a high level</li> <li>• When 1 is written, SDA pin changes to Hi-Z output (high output by external pull-up resistor)</li> </ul>
4	SDAOP	0	R/W	SDAO write protection This bit controls changes in the output level of the SDA pin by changing the SDAO bit value. To change the output level, use the MOV instruction to clear SDAO and SDAOP to 0 or set SDAO to 1 and clear SDAOP to 0. This bit is always read as 1.

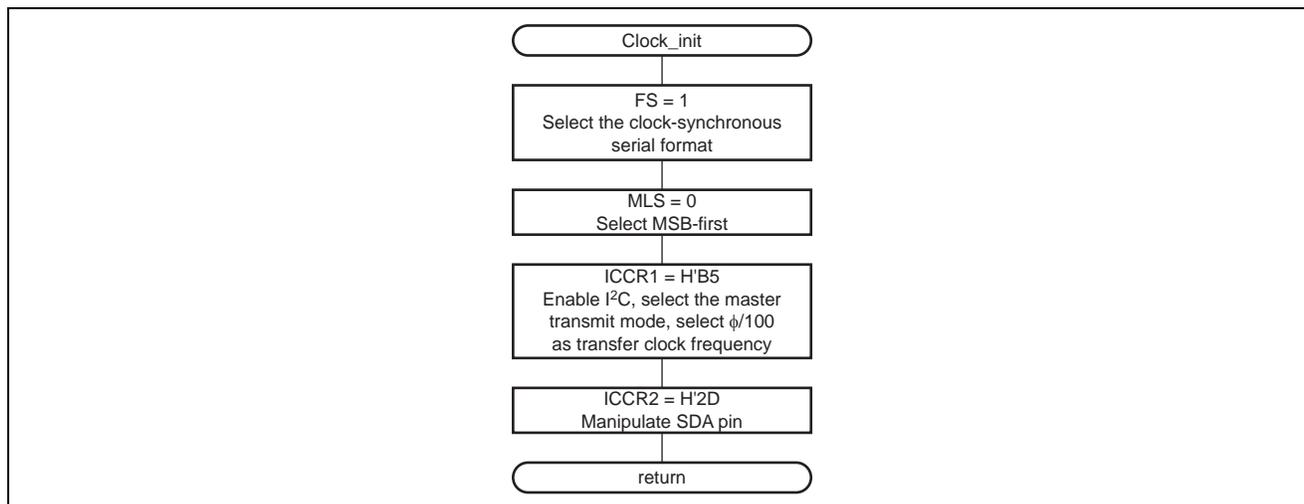
- ICMR I<sup>2</sup>C bus mode register Address: H'F07A

Bit	Bit Name	Set Value	R/W	Description
7	MLS	0	R/W	MSB-first/LSB-first selection 0: MSB-first 1: LSB-first

- SAR Slave address register Address: H'F07D

Bit	Bit Name	Set Value	R/W	Description
0	FS	1	R/W	Format selection 0: I <sup>2</sup> C bus format selected 1: Clock-synchronous serial format selected

### 3. Flowchart



### 5.4.3 master\_trsr() Function

#### 1. Module Specifications

- Master transmit operation

**Table 8 Module Specifications**

Item	Type	Variable	Description
Arguments	None	None	None

#### 2. Internal Registers Used

The internal registers used in this sample task are shown below. The set values shown are those used in the sample task and differ from the initial values.

- ICCR1                      I<sup>2</sup>C bus control register 1                      Address: H'F078

Bit	Bit Name	Set Value	R/W	Description
5	MST	1	R/W	Master/slave selection
4	TRS	1	R/W	Transmit/receive selection The value of the TRS bit should be changed between transfer frames. The following operation modes can be selected by the MST and TRS bits in combination. 00: Slave receive mode 01: Slave transmit mode 10: Master receive mode 11: Master transmit mode

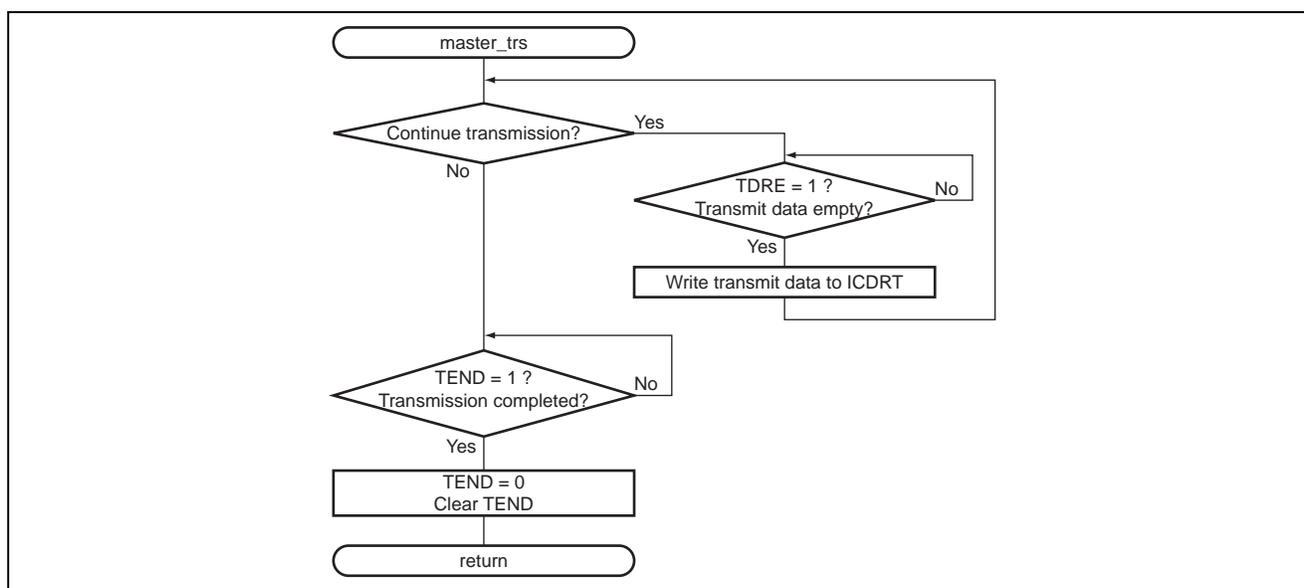
- ICSR                      I<sup>2</sup>C bus status register                      Address: H'F07C

Bit	Bit Name	Set Value	R/W	Description
7	TDRE	Undefined	R/W	Transmit data register empty [Setting conditions] <ul style="list-style-type: none"> <li>• When data is transferred from ICDRT to ICDRS and ICDRT becomes empty</li> <li>• When the TRS bit is set to 1</li> </ul> [Clearing conditions] <ul style="list-style-type: none"> <li>• When 0 is written to TDRE after it was read as 1</li> <li>• When data is written to ICDRT with an instruction</li> </ul>
6	TEND	Undefined	R/W	Transmit end [Setting condition] <ul style="list-style-type: none"> <li>• When the rising edge of the ninth clock cycle of SCL is detected while the value of TDRE is 1</li> </ul> [Clearing conditions] <ul style="list-style-type: none"> <li>• When 0 is written in TEND after it was read as 1</li> <li>• When data is written to ICDRT with an instruction</li> </ul>

- ICDRT                      I<sup>2</sup>C bus transmit data register                      Address: H'F07E

Bit	Bit Name	Set Value	R/W	Description
7	Bit 7	Undefined	R/W	I <sup>2</sup> C bus transmit data register
6	Bit 6	Undefined	R/W	ICDRT is an 8-bit readable/writable register that stores transmit data. When ICDRT detects space in the I <sup>2</sup> C bus shift register (ICDRS) it transfers the transmit data which has been written to ICDRT to ICDRS and starts transferring data. Continuous transfer is possible if the next transmit data is written to ICDRT while data transfer to ICDRS is in progress. The initial value of ICDRT is H'FF.
5	Bit 5	Undefined	R/W	
4	Bit 4	Undefined	R/W	
3	Bit 3	Undefined	R/W	
2	Bit 2	Undefined	R/W	
1	Bit 1	Undefined	R/W	
0	Bit 0	Undefined	R/W	

### 3. Flowchart



### 5.4.4 master\_rcv() Function

#### 1. Module Specifications

- Master receive operation

**Table 9 Module Specifications**

Item	Type	Variable	Description
Arguments	None	None	None
Return value	unsigned char	-	0: No error 1: Error

#### 2. Internal Registers Used

The internal registers used in this sample task are shown below. The set values shown are those used in the sample task and differ from the initial values.

- ICCR1                      I<sup>2</sup>C bus control register 1                      Address: HF078

Bit	Bit Name	Set Value	R/W	Description
6	RCVD	0	R/W	Reception disabled This bit enables or disables the next operation when TRS is 0 and ICDRR is read. 0: Enables next reception 1: Disables next reception
5	MST	1	R/W	Master/slave selection
4	TRS	0	R/W	Transmit/receive selection In the master mode with the I <sup>2</sup> C bus format, MST and TRS are both reset by hardware when arbitration is lost, causing a transition to the slave receive mode. The value of the TRS bit should be changed between transfer frames. The following operation modes can be selected by the MST and TRS bits in combination. 00: Slave receive mode 01: Slave transmit mode 10: Master receive mode 11: Master transmit mode

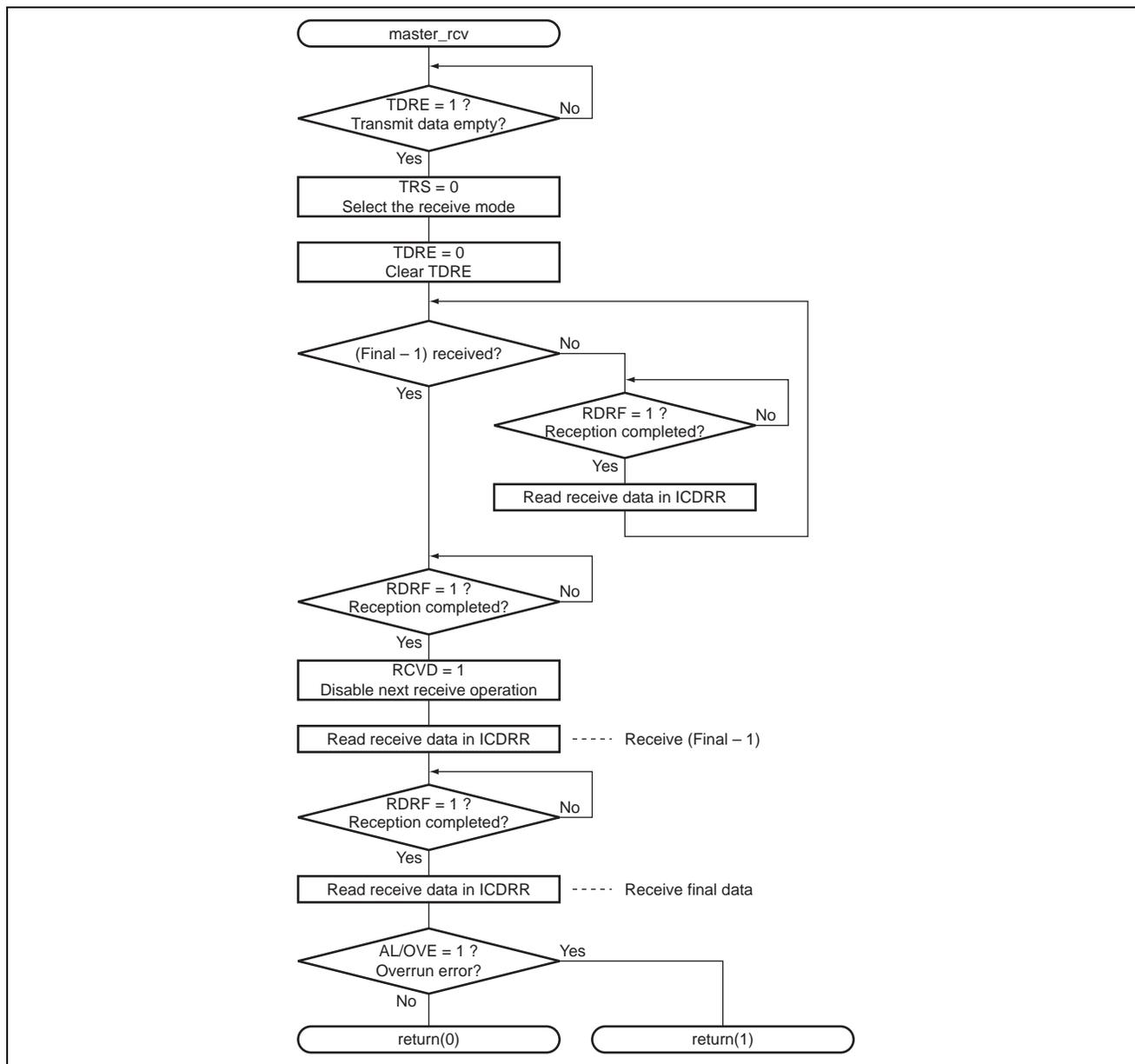
- ICSR                                      I<sup>2</sup>C bus status register                                      Address: H'F07C

Bit	Bit Name	Set Value	R/W	Description
7	TDRE	Undefined	R/W	Transmit data register empty [Setting conditions] <ul style="list-style-type: none"> <li>• When data is transferred from ICDRT to ICDRS and ICDRT becomes empty</li> <li>• When the TRS bit is set to 1</li> <li>• When a start condition (including re-transfer) has been issued</li> </ul> [Clearing conditions] <ul style="list-style-type: none"> <li>• When 0 is written to TDRE after it was read as 1</li> <li>• When data is written to ICDRT with an instruction</li> </ul>
5	RDRF	Undefined	R/W	Receive data register full [Setting condition] <ul style="list-style-type: none"> <li>• When receive data is transferred from ICDRS to ICDRR</li> </ul> [Clearing conditions] <ul style="list-style-type: none"> <li>• When 0 is written to RDRF after it was read as 1</li> <li>• When ICDRR is read with an instruction</li> </ul>
2	AL/OVE	Undefined	R/W	Arbitration lost flag/overrun error flag In the clock-synchronous serial format this flag indicates that the final bit has been received while RDRF remains 1. [Setting condition] <ul style="list-style-type: none"> <li>• When the final bit is received while RDRF remains 1</li> </ul> [Clearing condition] <ul style="list-style-type: none"> <li>• When 0 is written to AL/OVE after it was read as 1</li> </ul>

- ICDRR                                      I<sup>2</sup>C bus receive data register                                      Address: H'F07F

Bit	Bit Name	Set Value	R/W	Description
7	Bit 7	Undefined	R	I <sup>2</sup> C bus receive data register
6	Bit 6	Undefined	R	ICDRR is an 8-bit register that stores receive data. After one byte of data is received, ICDRR transfers the receive data from ICDRS to ICDRR and the next data can be received. ICDRR is a receive-only register, so the CPU cannot write to it. The initial value of ICDRR is H'FF.
5	Bit 5	Undefined	R	
4	Bit 4	Undefined	R	
3	Bit 3	Undefined	R	
2	Bit 2	Undefined	R	
1	Bit 1	Undefined	R	
0	Bit 0	Undefined	R	

#### 3. Flowchart



### 5.5 Link Address Specifications

Section Name	Address
CVECT	H'0000
P	H'0100
D, B	H'F780

## 6. Description of Software (Slave)

In this sample task I<sup>2</sup>C bus interface module initialization, slave receive, and slave transmit operations are performed. The functions used by the slave program are described below.

### 6.1 Functions

**Table 10 List of Slave Program Functions**

Function Name	Description
main	Controls slave communication
IIC2_init	Initializes the I <sup>2</sup> C clock-synchronous serial format
slave_rcv	Slave receive operation
slave_trs	Slave transmit operation

### 6.2 Constants

Table 11 shows the constants used in this sample task.

**Table 11 Constants**

Label Name	Constant Value	Description	Used in
SIZE	4	Transmit/receive data size	slave_trs slave_rcv

### 6.3 RAM Usage

Table 12 shows the RAM used in this sample task.

**Table 12 RAM Usage**

Label Name	Description	Memory Consumption	Used in
s_data[SIZE]	Buffer for storing transmit/receive data	4 bytes	slave_trs slave_rcv

## 6.4 Modules

### 6.4.1 main() Function

1. Module Specifications
  - Controls slave communication

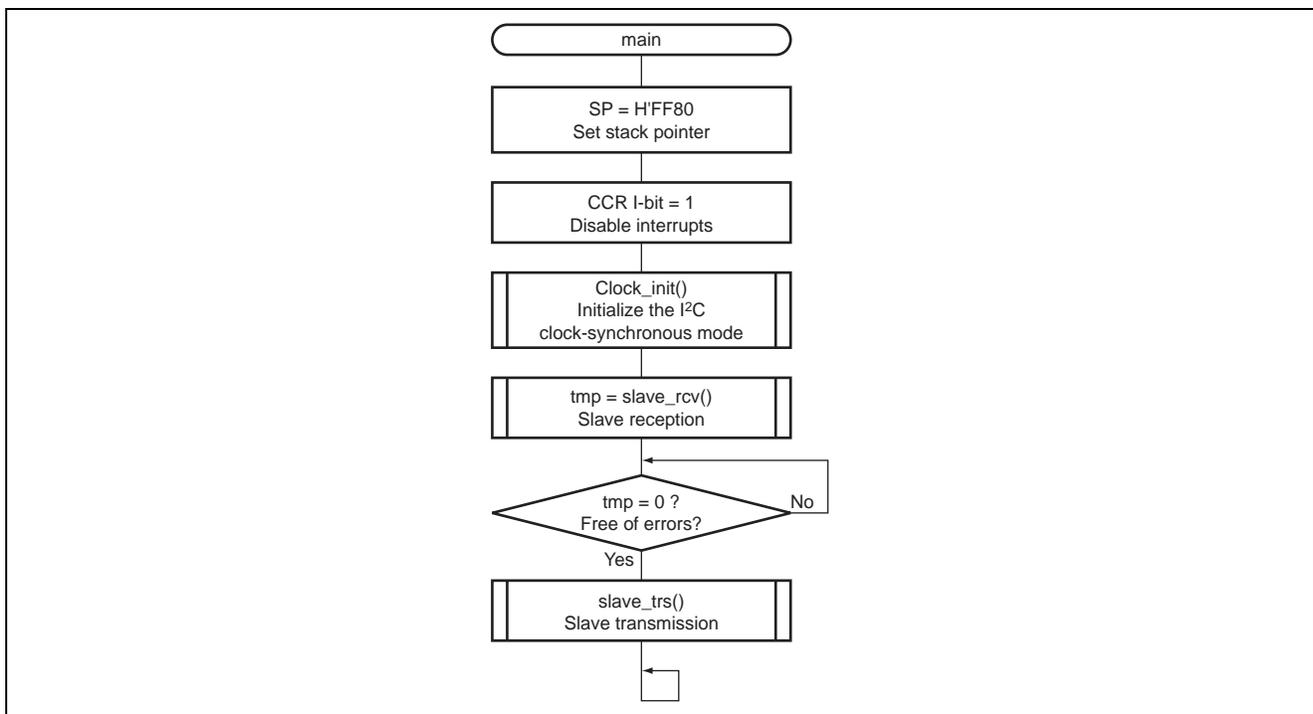
**Table 13 Module Specifications**

Item	Type	Variable	Description
Arguments	None	None	None

2. Internal Registers Used

None

3. Flowchart



## 6.4.2 Clock\_init() Function

### 1. Module Specifications

- Initializes the I<sup>2</sup>C clock-synchronous serial format

**Table 14 Module Specifications**

Item	Type	Variable	Description
Arguments	None	None	None

### 2. Internal Registers Used

The internal registers used in this sample task are shown below. The set values shown are those used in the sample task and differ from the initial values.

- ICCR1                      I<sup>2</sup>C bus control register 1                      Address: H'F078

Bit	Bit Name	Set Value	R/W	Description
7	ICE	1	R/W	I <sup>2</sup> C bus interface 2 enabled 0: The module is halted. (SCL and SDA pins are set to the port/serial function.) 1: The module is enabled for transfer operations. (SCL and SDA pins are bus drive state.)
6	RCVD	0	R/W	Reception disabled This bit enables or disables the next operation when TRS is 0 and ICDRR is read. 0: Enables next reception 1: Disables next reception
5	MST	0	R/W	Master/slave selection
4	TRS	0	R/W	Transmit/receive selection In the master mode with the I <sup>2</sup> C bus format, MST and TRS are both reset by hardware when arbitration is lost, causing a transition to the slave receive mode. The value of the TRS bit should be changed between transfer frames. The following operation modes can be selected by the MST and TRS bits in combination. 00: Slave receive mode 01: Slave transmit mode 10: Master receive mode 11: Master transmit mode

- ICCR2 I<sup>2</sup>C bus control register 2 Address: H'F079

Bit	Bit Name	Set Value	R/W	Description
5	SDAO	1	R/W	SDA output value control This bit is used with SDAOP (bit 4) when changing the output level of SDA. This bit should not be manipulated when a transfer is in progress. <ul style="list-style-type: none"> <li>• When 0 is read, SDA pin outputs a low level</li> <li>• When 0 is written, SDA pin changes to low level output</li> <li>• When 1 is read, SDA pin outputs a high level</li> <li>• When 1 is written, SDA pin changes to Hi-Z output (high output by external pull-up resistor)</li> </ul>
4	SDAOP	0	R/W	SDAO write protection This bit controls changes in the output level of the SDA pin by modifying the SDAO bit. To change the output level, use the MOV instruction to clear SDAO and SDAOP to 0 or set SDAO to 1 and clear SDAOP to 0. This bit is always read as 1.

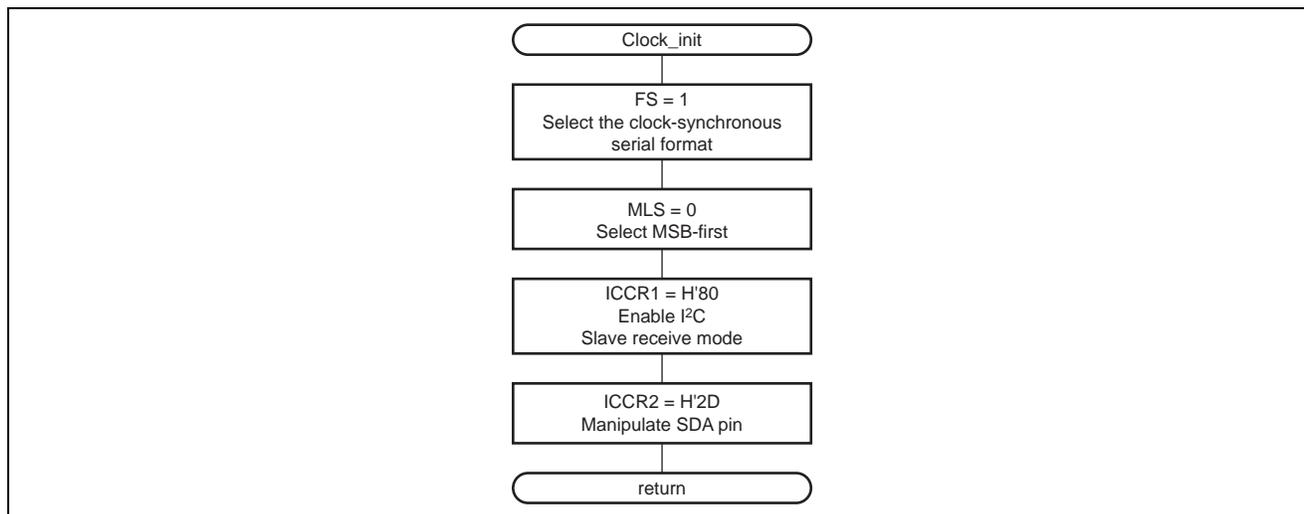
- ICMR I<sup>2</sup>C bus mode register Address: H'F07A

Bit	Bit Name	Set Value	R/W	Description
7	MLS	0	R/W	MSB-first/LSB-first select 0: MSB-first 1: LSB-first

- SAR Slave address register Address: H'F07D

Bit	Bit Name	Set Value	R/W	Description
0	FS	1	R/W	Format selection 0: I <sup>2</sup> C bus format selected 1: Clock-synchronous serial format selected

### 3. Flowchart



### 6.4.3 slave\_rcv() Function

1. Module Specifications
  - Slave receive operation

**Table 15 Module Specifications**

Item	Type	Variable	Description
Arguments	None	None	None

2. Internal Registers Used

The internal registers used in this sample task are shown below. The set values shown are those used in the sample task and differ from the initial values.

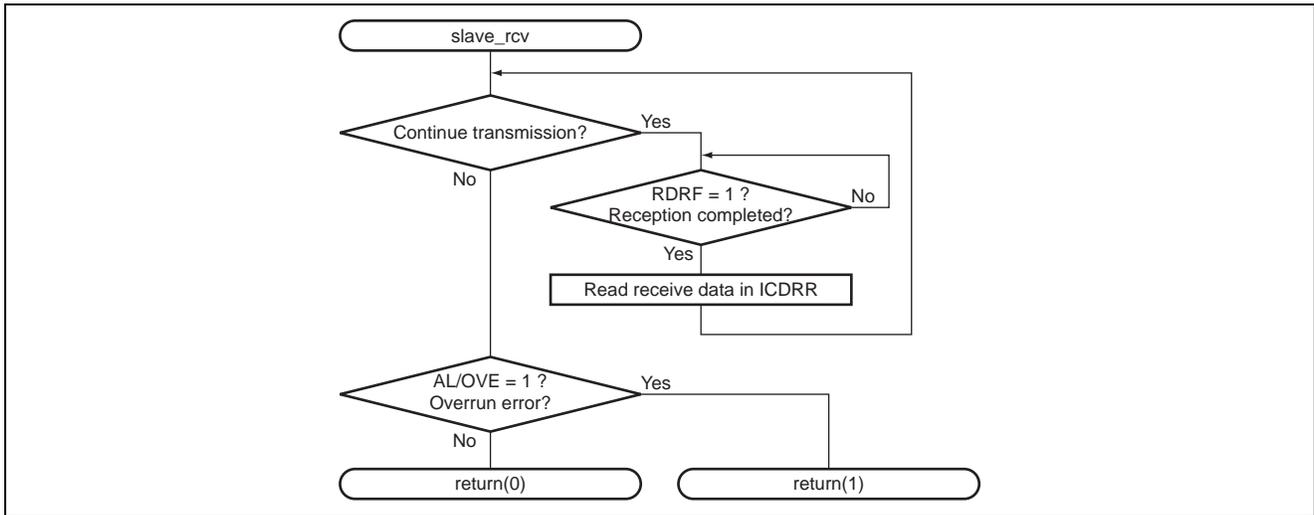
- ICSR                              I<sup>2</sup>C bus status register                              Address: H'F07C

Bit	Bit Name	Set Value	R/W	Description
5	RDRF	Undefined	R/W	Receive data register full [Setting condition] <ul style="list-style-type: none"> <li>• When receive data is transferred from ICDRS to ICDRR</li> <li>[Clearing conditions]               <ul style="list-style-type: none"> <li>• When 0 is written to RDRF after it was read as 1</li> <li>• When ICDRR is read with an instruction</li> </ul> </li> </ul>
2	AL/OVE	Undefined	R/W	Arbitration lost flag/overflow error flag In the clock-synchronous serial format this flag indicates that the final bit has been received while RDRF remains 1. [Setting condition] <ul style="list-style-type: none"> <li>• When the final bit is received while RDRF remains 1</li> <li>[Clearing condition]               <ul style="list-style-type: none"> <li>• When 0 is written to AL/OVE after it was read as 1</li> </ul> </li> </ul>

- ICDRR                              I<sup>2</sup>C bus receive data register                              Address: H'F07F

Bit	Bit Name	Set Value	R/W	Description
7	Bit 7	Undefined	R	I <sup>2</sup> C bus receive data register ICDRR is an 8-bit register that stores receive data. After one byte of data is received, ICDRR transfers the receive data from ICDRS to ICDRR and the next data can be received. ICDRR is a receive-only register, so the CPU cannot write to it. The initial value of ICDRR is H'FF.
6	Bit 6	Undefined	R	
5	Bit 5	Undefined	R	
4	Bit 4	Undefined	R	
3	Bit 3	Undefined	R	
2	Bit 2	Undefined	R	
1	Bit 1	Undefined	R	
0	Bit 0	Undefined	R	

3. Flowchart



### 6.4.4 slave\_tris() Function

#### 1. Module Specifications

- Slave transmit operation

**Table 16 Module Specifications**

Item	Type	Variable	Description
Arguments	None	None	None

#### 2. Internal Registers Used

The internal registers used in this sample task are shown below. The set values shown are those used in the sample task and differ from the initial values.

- ICCR1                      I<sup>2</sup>C bus control register 1                      Address: H'F078

Bit	Bit Name	Set Value	R/W	Description
5	MST	0	R/W	Master/slave selection
4	TRS	1	R/W	Transmit/receive selection The value of the TRS bit should be changed between transfer frames. The following operation modes can be selected by the MST and TRS bits in combination. 00: Slave receive mode 01: Slave transmit mode 10: Master receive mode 11: Master transmit mode

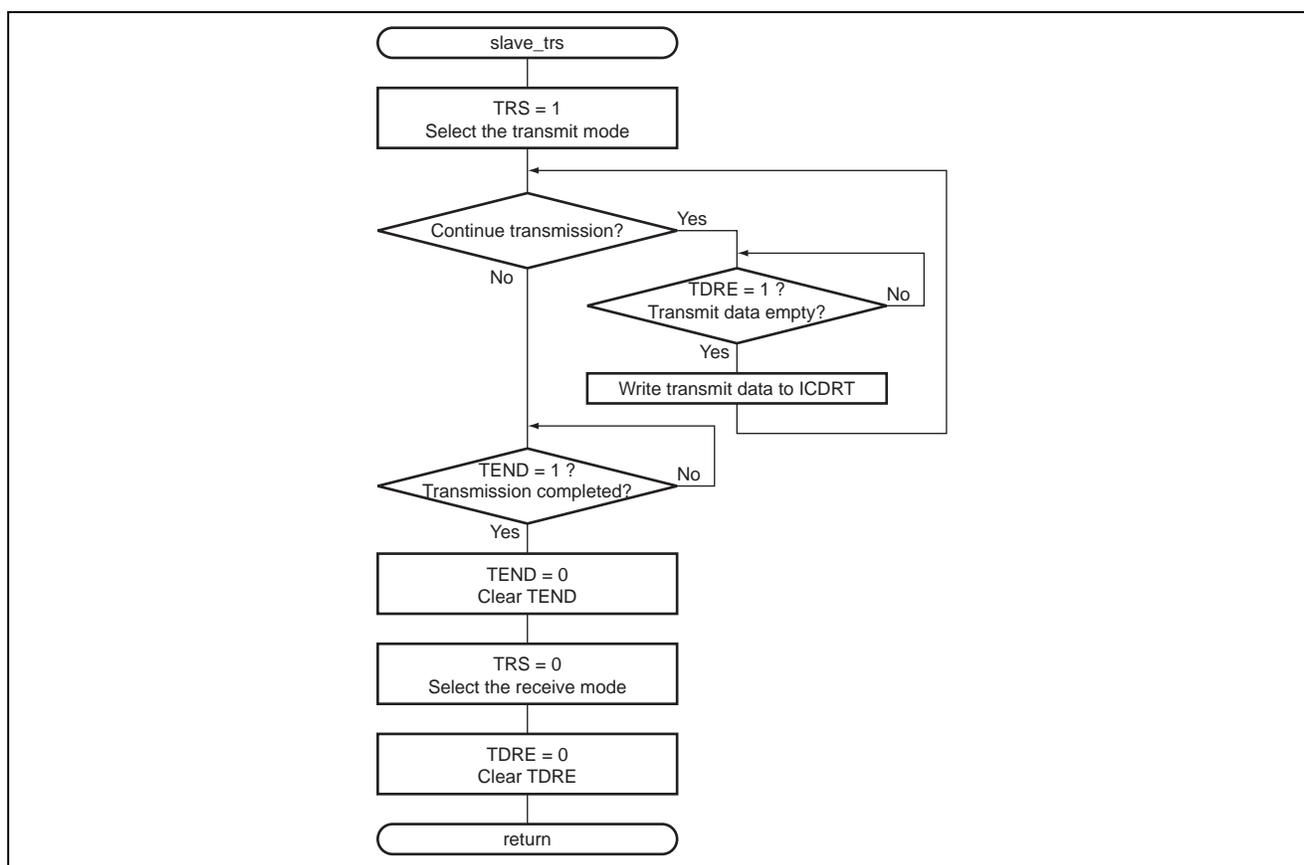
- ICSR                      I<sup>2</sup>C bus status register                      Address: H'F07C

Bit	Bit Name	Set Value	R/W	Description
7	TDRE	Undefined	R/W	Transmit data register empty [Setting conditions] <ul style="list-style-type: none"> <li>• When data is transferred from ICDRT to ICDRS and ICDRT becomes empty</li> <li>• When the TRS bit is set to 1</li> </ul> [Clearing conditions] <ul style="list-style-type: none"> <li>• When 0 is written to TDRE after it was read as 1</li> <li>• When data is written to ICDRT with an instruction</li> </ul>
6	TEND	Undefined	R/W	Transmit end [Setting condition] <ul style="list-style-type: none"> <li>• When the rising edge of the ninth clock cycle of SCL is detected while the value of TDRE is 1</li> </ul> [Clearing conditions] <ul style="list-style-type: none"> <li>• When 0 is written in TEND after it was read as 1</li> <li>• When data is written to ICDRT with an instruction</li> </ul>

- ICDRT I<sup>2</sup>C bus transmit data register Address: H'F07E

Bit	Bit Name	Set Value	R/W	Description
7	Bit 7	Undefined	R/W	I <sup>2</sup> C bus transmit data register
6	Bit 6	Undefined	R/W	ICDRT is an 8-bit readable/writable register that stores transmit data. When ICDRT detects space in the I <sup>2</sup> C bus shift register (ICDRS) it transfers the transmit data which was written to ICDRT to ICDRS and starts transferring data. Continuous transfer is possible if the next transmit data is written to ICDRT while data transfer to ICDRS is in progress. The initial value of ICDRT is H'FF.
5	Bit 5	Undefined	R/W	
4	Bit 4	Undefined	R/W	
3	Bit 3	Undefined	R/W	
2	Bit 2	Undefined	R/W	
1	Bit 1	Undefined	R/W	
0	Bit 0	Undefined	R/W	

### 3. Flowchart



## 6.5 Link Address Specifications

Section Name	Address
CVECT	H'0000
P	H'0100
B	H'F780

### Revision Record

Rev.	Date	Description	
		Page	Summary
1.00	Mar.18.05	—	First edition issued

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