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April 1st, 2010
Renesas Electronics Corporation

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H8/300H Tiny Series

Entering Low Power Consumption Mode (H8/3687)

Introduction

The switching function for low power consumption modes of the H8/3687 Group products allows the user to choose from among five different modes: active, sub-active, sleep, sub-sleep, and standby.

Target Device

H8/3687

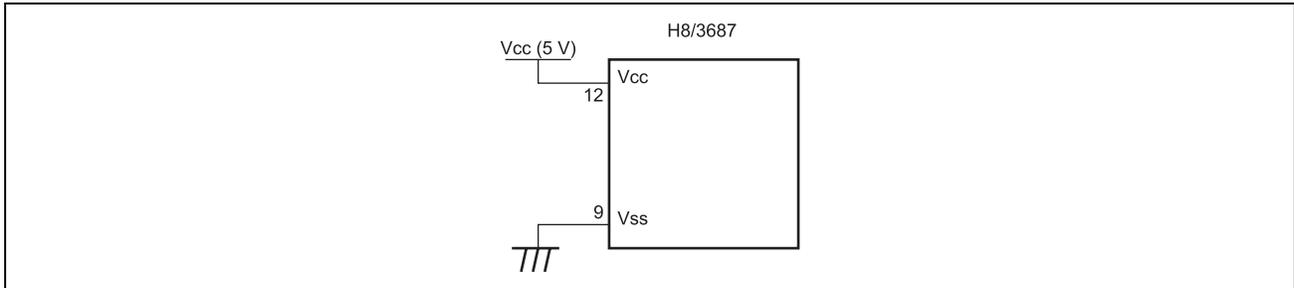
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1. Overview

By means of a function for switching between H8/3687 low power consumption modes, switching between active, sub-active, sleep, sub-sleep, and standby modes is performed.

2. Configuration



Specifications

H8/3687 operating frequency: 16 MHz

3. Sample Program

3.1 Functions

- Direct transitions are made into active and sub-active modes.
- Transitions are made into sleep, sub-sleep, and standby modes. Interrupts are used to return to active and sub-active modes at the specified operating frequency.

3.2 Program incorporation

- Sample program 2-A
Incorporate #define directives.
- Sample program 2-B
Incorporate prototype declarations.
- Sample program 2-C
Add the sample program 2-C as the common routine.

3.3 Modifications to sample programs

Without modifications to the sample program, the system may not run. Modifications must be made according to the customer's program and system environment.

- By using a file with definitions of IO register structures which can be obtained free of charge from the Renesas web site, the sample program can be used without further changes. When creating definitions independently, the customer should modify the IO register structures used in the sample program as appropriate.

3.4 Method of use

- The operating frequency is changed.

```
com_frequency_change (int return_mode, int frequency)
```

| Argument | Description |
|-------------|--|
| return_mode | Specifies the operating mode after the frequency is changed. ACTIVE_MODE(0): Active mode SUB_ACTIVE_MODE(1): Sub-active mode |
| frequency | Indicates the operating frequency after the change. OSC_PER_1 (0x00): ϕ (In this sample program, setting is 16 MHz) OSC_PER_8 (0x10): $\phi/8$ (In this sample program, setting is 2 MHz)* OSC_PER_16 (0x14): $\phi/16$ (In this sample program, setting is 1 MHz)* OSC_PER_32 (0x18): $\phi/32$ (In this sample program, setting is 0.5 MHz)* OSC_PER_64 (0x1C): $\phi/64$ (In this sample program, setting is 0.25 MHz)* OSC_PER_W8 (0x00): $\phi w/8$ (4.096 kHz) OSC_PER_W4 (0x01): $\phi w/4$ (8.192 kHz) OSC_PER_W2 (0x02): $\phi w/2$ (16.384 kHz) Note: * Settings resulting in a frequency of less than 78.125 kHz (the minimum operating frequency) are not possible. Example: When $\phi=4$ MHz, $\phi/64=62.5$ kHz, and so OSC_PER_64 (0x1C) cannot be specified. |

Example of use:

```
/* disable SCI3 reception interrupts */
SCI3.SCR3.BYTE = 0x10;
/* invalidate TimerZ interrupts */
TZ0.TIER.BIT.IMIEA = 0;
/* change the frequency */
com_frequency_change (ACTIVE_MODE, OSC_PER_8);
// return using a direct transition interrupt
// make transition to active mode, operating frequency  $\phi/8$ 
```

- Make a transition to sleep/sub-sleep/standby mode. When an interrupt occurs, return to active/sub-active mode at the specified operating frequency.

```
com_mode_change (int stop_mode, int return_mode, int frequency)
```

| Argument | Description |
|-------------|--|
| stop_mode | Specifies a stop mode. SLEEP_MODE(0): Sleep mode SUB_SLEEP_MODE(1): Sub-sleep mode STANDBY_MODE(2): Standby mode |
| return_mode | Specifies the operating mode after the frequency is changed. ACTIVE_MODE(0): Active mode SUB_ACTIVE_MODE(1): Sub-active mode |
| frequency | Indicates the operating frequency after the change. OSC_PER_1 (0x00): ϕ (In this sample program, setting is 16 MHz) OSC_PER_8 (0x10): $\phi/8$ (In this sample program, setting is 2 MHz)* OSC_PER_16 (0x14): $\phi/16$ (In this sample program, setting is 1 MHz)* OSC_PER_32 (0x18): $\phi/32$ (In this sample program, setting is 0.5 MHz)* OSC_PER_64 (0x1C): $\phi/64$ (In this sample program, setting is 0.25 MHz)* OSC_PER_W8 (0x00): $\phi w/8$ (4.096 kHz) OSC_PER_W4 (0x01): $\phi w/4$ (8.192 kHz) OSC_PER_W2 (0x02): $\phi w/2$ (16.384 kHz) Note: * Settings resulting in a frequency of less than 78.125 kHz (the minimum operating frequency) are not possible. Example: When $\phi = 4$ MHz, $\phi/64 = 62.5$ kHz, and so OSC_PER_64 (0x1C) cannot be specified. |

Example of use:

```
/* disable SCI3 reception interrupts */
SCI3.SCR3.BYTE = 0x10;
/* invalidate TimerZ interrupts */
TZ0.TIER.BIT.IMIEA = 0;
/* enable int 0*/
IENR1.BIT.IEN0 = 1;
com_mode_change (SLEEP_MODE, ACTIVE_MODE, OSC_PER_1);
// enter sleep mode; return on int0 interrupt
// active mode, return at frequency  $\phi$ 
```

Important information: When making a transition to sub-active mode, operation is limited as follows.

- The RTC interval timer cannot be used.
- The watchdog timer, I²C, timer B1, and timer Z cannot be used.
- The timer V, SCI3, and A/D converter are reset, and so the various registers should be rewritten as necessary.

3.5 Description of operation

Figure 1 shows the possible transitions between modes. A transition from a program execution state to a program halt state is made by executing a SLEEP instruction. An interrupt is used to return from the program halt state to the program execution state. Direct transitions can also be made between active mode and sub-active mode, which are program execution states, without stopping program execution. And, by making direct transitions from active mode to active mode, and from sub-active mode to sub-active mode, the operating frequency can be changed in the same mode. A transition from all modes to the reset state is made through RES input. Table 1 indicates transition conditions to various modes when the SLEEP instruction is executed, as well as return destinations resulting from an interrupt; Table 2 describes the internal states of the LSI device in each of the operating modes.

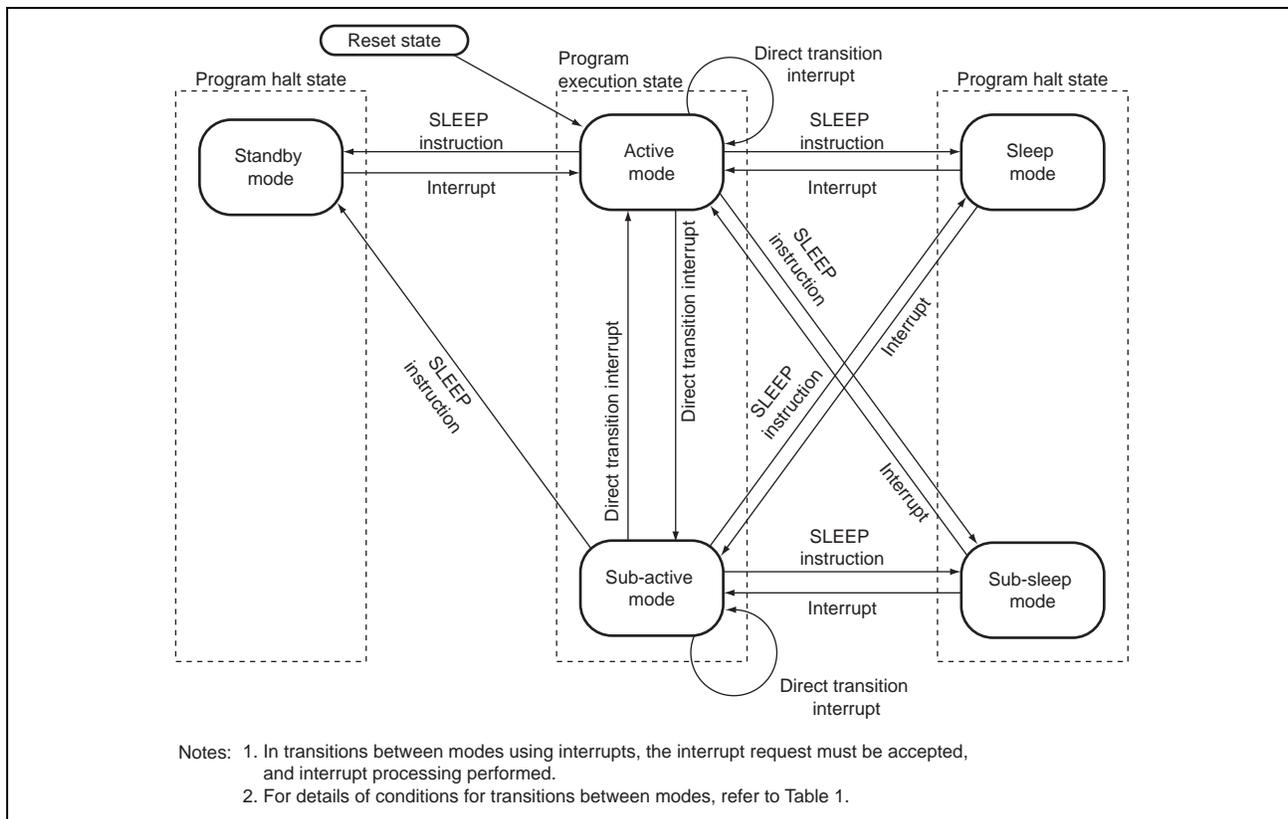


Figure 1 Mode transition diagram

Table 1 States upon SLEEP instruction execution and return destinations on interrupt

| SYSCR1 | | SYSCR2 | | States upon SLEEP Instruction Execution | Return Destination on Interrupt |
|--------|------|--------|------|---|---------------------------------|
| DTON | SSBY | SMSEL | LSON | | |
| 0 | 0 | 0 | 0 | Sleep mode | Active mode |
| 0 | 0 | 0 | 1 | Sleep mode | Sub-active mode |
| 0 | 0 | 1 | 0 | Sub-sleep mode | Active mode |
| 0 | 0 | 1 | 1 | Sub-sleep mode | Sub-active mode |
| 0 | 1 | × | × | Standby mode | Active mode |
| 1 | × | 0* | 0 | Active mode (direct transition) | X |
| 1 | × | × | 1 | Sub-active mode (direct transition) | |

[Legend] ×: Don't care

Note: * When making a state transition with SMSEL=1, the timer V, SCI3, and A/D converter are set, and the values in registers are returned to the initial values. After a transition to active mode, when using these functions the register values must be rewritten.

Table 2 LSI states in different operating modes

| Function | Active | Sleep | Sub-active | Sub-sleep | Standby | |
|-------------------------|-----------------------|----------|------------|--|--|----------|
| System clock oscillator | Operates | Operates | Stop | Stop | Stop | |
| Sub-clock oscillator | Operates | Operates | Operates | Operates | Operates | |
| CPU | Instruction execution | Operates | Stop | Operates | Stop | Stop |
| | Register | Operates | Held | Operates | Held | Held |
| RAM | Operates | Held | Operates | Held | Held | |
| I/O port | Operates | Held | Operates | Held | Registers held; output at high impedance | |
| External interrupt | IRQ3 to IRQ0 | Operates | Operates | Operates | Operates | Operates |
| | WKP5 to WKP0 | Operates | Operates | Operates | Operates | Operates |
| Peripheral module | RTC | Operates | Operates | Operates when clock time base function selected; held when interval timer selected | | |
| | Timer V | Operates | Operates | Reset | Reset | Reset |
| | Watchdog timer | Operates | Operates | Held (however, operates when internal oscillator selected for counter clock*) | | |
| | SCI3, SCI3_2 | Operates | Operates | Reset | Reset | Reset |
| | IIC2 | Operates | Operates | Held* | Held | Held |
| | Timer B1 | Operates | Operates | Held* | Held | Held |
| | Timer Z | Operates | Operates | Held* | Held | Held |
| A/D converter | Operates | Operates | Reset | Reset | Reset | |

Note: * In sub-active mode, register read/write is possible.

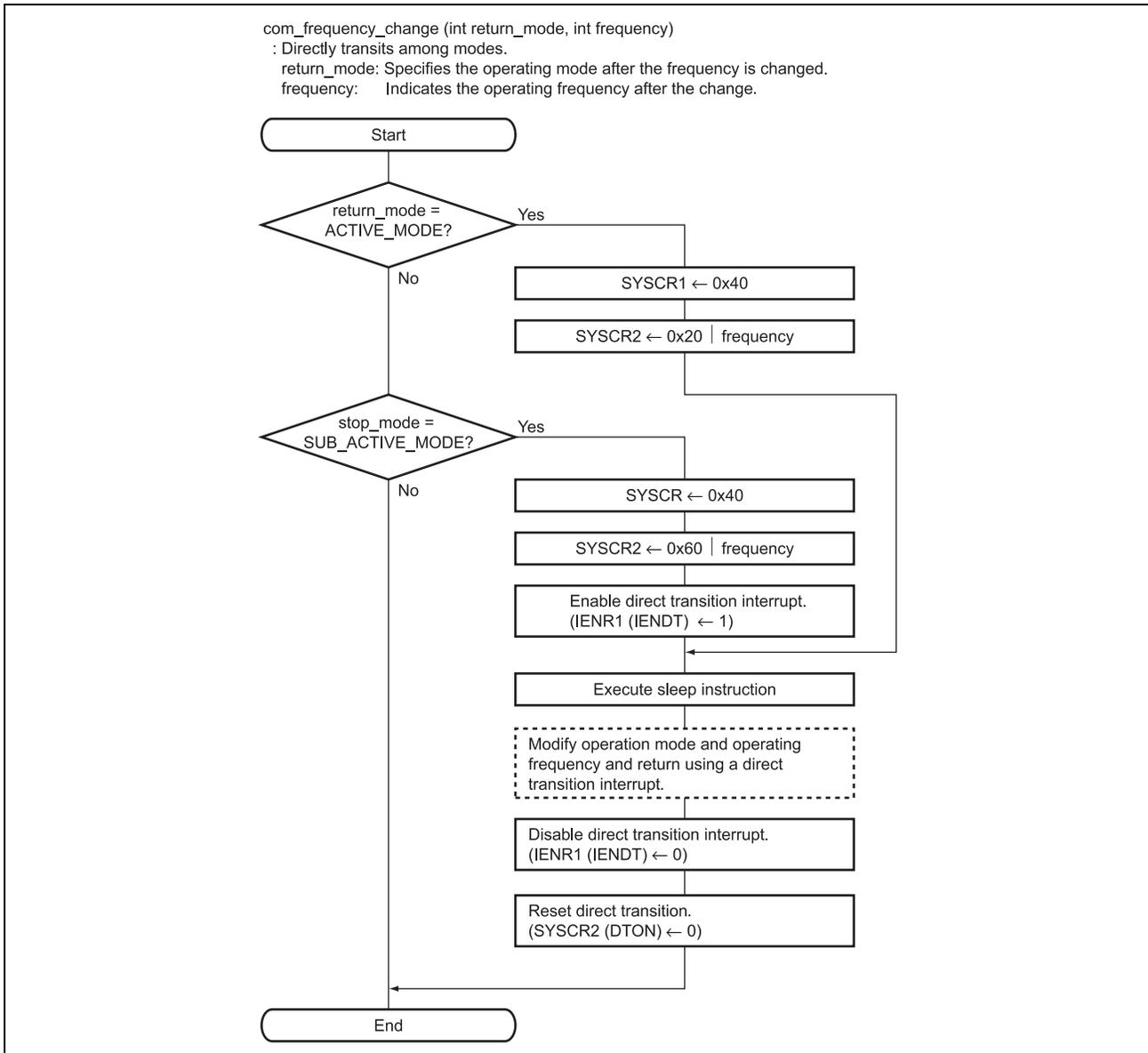
3.6 List of registers used

The H8 microcomputer internal registers used in this sample program are listed. For details, refer to the H8/3687 Group Hardware Manual.

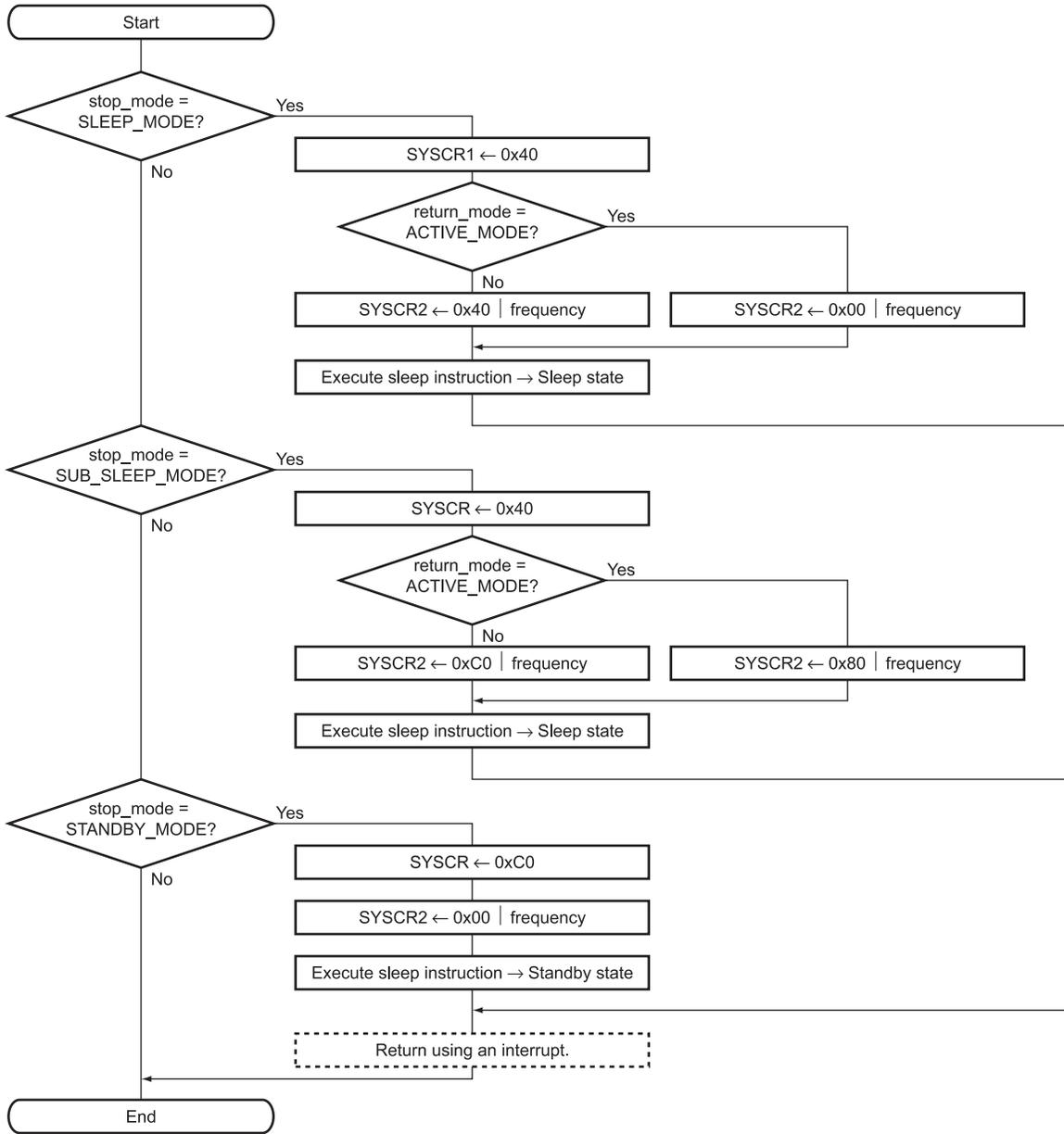
| Name | Description |
|------------------------------------|--------------------------------------|
| System control register 1 (SYSCR1) | Controls low power consumption modes |
| System control register 2 (SYSCR2) | Controls low power consumption modes |

3.7 Flowcharts

The flow of program execution is indicated below.



com_mode_change (int stop_mode, int return_mode, int frequency)
 : Makes transition among modes.
 stop_mode: Specifies a stop mode.
 return_mode: Specifies the operating mode after the frequency is changed.
 frequency: Indicates the operating frequency after the change.



3.8 Program Listing

```

/* ----- */
/* ----- */
/* 1. Sample Program 11-A #define directives ----- */
/* ----- */
/* ----- */

/*****
/* For frequency and mode modification */
/*****
#define OSC_PER_1      0x00
#define OSC_PER_8      0x10
#define OSC_PER_16     0x14
#define OSC_PER_32     0x18
#define OSC_PER_64     0x1C
#define OSC_PER_W8     0x00
#define OSC_PER_W4     0x01
#define OSC_PER_W2     0x02

#define ACTIVE_MODE    0
#define SUB_ACTIVE_MODE 1

#define SLEEP_MODE     0
#define SUB_SLEEP_MODE 1
#define STANDBY_MODE   2

/* ----- */
/* ----- */
/* 2. Sample program 11-B Prototype declaration ----- */
/* ----- */
/* ----- */

/* Mode modification processing */
void com_mode_change (int stop_mode , int return_mode , int frequency) ;
void com_frequency_change (int return_mode , int frequency ) ;

```

```

/* ----- */
/* ----- */
/* 4. Sample program 11-C Common source codes ----- */
/* ----- */
/* ----- */

/*****
/*****
/*****
/*
/*          Low power consumption mode
/*
/*
/*****
/*****
/*****

/*****
/* 1. Module name: com_mode_change
/* 2. Function overview: Performs a mode transition
/* Parameter combination
/* stop_mode      return_mode      frequency
/* SLEEP_MODE    → ACTIVE_MODE     OSC_PER_1/8/16/32/64
/* SLEEP_MODE    → SUB_ACTIVE_MODE  OSC_PER_W8/4/2
/* SUB_SLEEP_MODE → ACTIVE_MODE     OSC_PER_1/8/16/32/64
/* SUB_SLEEP_MODE → SUB_ACTIVE_MODE OSC_PER_W8/4/2
/* STANDBY_MODE  → ACTIVE_MODE     OSC_PER_1/8/16/32/64
/*
/*****

void com_mode_change (int stop_mode , int return_mode , int frequency )
{

    switch (stop_mode){
        case SLEEP_MODE :
            /*****
            /* Sets SYSCR1 :
            /*     SSBSY   = 0 Enters sleep mode during sleep instruction execution
            /*     STS2:0   = 100 specifies the wait time for clock stabilization from standby to sleep as 8.2 ms.
            /*     NESEL    = 0 specifies the noise elimination sampling frequency as 8 MHzk/16.
            /*****
            SYSCR1.BYTE = 0x40 ;

            /*****
            /* Sets SYSCR2 :
            /*     SMSEL    = 0 Enters sleep mode
            /*     LSON     = 0/1
            /*     DTON     = 0 Disables direct transition during sleep instruction execution
            /*     MA2:0    = 000 Selects the main clock operating frequency (Specified by argument frequency)
            /*     SA1:0    = 00 Selects the sub-clock operating frequency (Specified by argument frequency)
            /*****
            if (return_mode == ACTIVE_MODE){
                SYSCR2.BYTE = 0x00 | frequency ;
            }
            else{
                SYSCR2.BYTE = 0x40 | frequency ;
            }
        }
    }
}

```

```

/*****
/*  Makes the device sleep and enters sleep mode.          */
/*****
sleep() ;

/* ===== */
/* === Returns here by an interrupt                          === */
/* ===== */

break ;

case SUB_SLEEP_MODE :
/*****
/*  Sets SYSCR1 :                                           */
/*      SSBSY      = 0 Enters sleep mode during sleep instruction execution          */
/*      STS2:0     = 100 specifies the wait time for clock stabilization from standby to sleep as 8.2 ms.          */
/*      NESEL      = 0 specifies the noise elimination sampling frequency as 8 MHzk/16.          */
/*****
SYSCR1.BYTE      = 0x40 ;

/*****
/*  Sets SYSCR2 :                                           */
/*      SMSSEL     = 1 Enters sub-sleep mode                                          */
/*      LSON       = 1/0                                                              */
/*      DTON       = 0 Disables direct transition during sleep instruction execution          */
/*      MA2:0      = 000 Selects the main clock operating frequency (Specified by argument frequency)          */
/*      SA1:0      = 00 Selects the sub-clock operating frequency (Specified by argument frequency)          */
/*****
if (return_mode == ACTIVE_MODE){
    SYSCR2.BYTE   = 0x80 | frequency ;
}
else{
    SYSCR2.BYTE   = 0xC0 | frequency ;
}

/*****
/*  Makes the device sleep and enters sleep mode.          */
/*****
sleep() ;

/* ===== */
/* === Returns here by an interrupt                          === */
/* ===== */

break ;

case STANDBY_MODE :
/*****
/*  Sets SYSCR1 :                                           */
/*      SSBSY      = 1 Makes a transition from sleep mode to standby mode          */
/*      STS2:0     = 100 specifies the wait time for clock stabilization from standby to sleep as 8.2 ms.          */
/*      NESEL      = 0 specifies the noise elimination sampling frequency as 8 MHzk/16.          */
/*****
SYSCR1.BYTE      = 0xC0 ;

```

```

/*****
/*  Sets SYSCR2 :
/*      SMSEL      = x
/*      LSON       = x
/*      DTON       = 0 Disables direct transition during sleep instruction execution
/*      MA2:0      = 000 Selects the main clock operating frequency (Specified by argument frequency)
/*      SA1:0      = 00 Selects the sub-clock operating frequency (Specified by argument frequency)
/*****
SYSCR2.BYTE = 0x00 | frequency ;

/*****
/*  Makes the device sleep and enters sleep mode.
/*****
sleep() ;
/* =====
/* === Returns here by an interrupt
/* =====

break ;

}

/*****
/*  1. Module name: com_frequency_change
/*  2. Function overview: Performs a mode transition
/*  Parameter combination
/*  return_mode      frequency
/*  ACTIVE_MODE      OSC_PER_1/8/16/32/64
/*  SUB_ACTIVE_MODE  OSC_PER_W8/4/2
/*
/*****
void com_frequency_change (int return_mode , int frequency )
{
    int i , j ;
    unsigned int    h8_addr;

    switch (return_mode){
        case ACTIVE_MODE :

            /*****
            /*  Sets SYSCR1 :
            /*      SSBSY      = 0
            /*      STS2:0     = 100 specifies the wait time for clock stabilization from standby to sleep as 8.2 ms.
            /*      NESEL      = 0 specifies the noise elimination sampling frequency as 8 MHzk/16.
            /*****
            SYSCR1.BYTE = 0x40 ;

```

```

/*****
/*  Sets SYSCR2 :
/*      SMSEL      = 0
/*      LSON       = 0
/*      DTON       = 1 Specifies a direct transition during sleep instruction execution
/*      MA2:0      = 000 Selects the main clock operating frequency (Specified by argument frequency)
/*      SA1:0      = 00 Selects the sub-clock operating frequency (Specified by argument frequency)
/*****
SYSCR2.BYTE = 0x20 | frequency ;

break ;

case SUB_ACTIVE_MODE :

/*****
/*  Sets SYSCR1 :
/*      SSBSY      = 0
/*      STS2:0     = 100 specifies the wait time for clock stabilization from standby to sleep as 8.2 ms.
/*      NESEL      = 0 specifies the noise elimination sampling frequency as 8 MHzk/16.
/*****
SYSCR1.BYTE = 0x40 ;

/*****
/*  Sets SYSCR2 :
/*      SMSEL      = 0 Not used
/*      LSON       = 1 Low-speed flag
/*      DTON       = 1 Specifies a direct transition during sleep instruction execution
/*      MA2:0      = 000 Selects the main clock operating frequency (Specified by argument frequency)
/*      SA1:0      = 00 Selects the sub-clock operating frequency (Specified by argument frequency)
/*****
SYSCR2.BYTE = 0x60 | frequency ;

break ;

}

/* Enables direct transition interrupts
IENR1.BIT.IENDT = 1 ;

/*****
/*  Makes the device sleep and generates a direct transition interrupt.
/*  Prepare the interrupt vector routine for direct transition .
/*****
sleep() ;

/* =====
/* == A direct transition interrupt occurs and the frequency switches to the specified frequency. ==
/* =====

/*****
/*  Cancels interrupt disable
/*****

/* Disables direct transition interrupts
IENR1.BIT.IENDT = 0 ;

/* Resets direct transitions
SYSCR2.BIT.DTON = 0 ;

}

```

4. Reference Documents

- H8/3687 Group Hardware Manual (published by Renesas Technology Corp.)

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Revision Record

| Rev. | Date | Description | |
|------|-----------|-------------|-------------------------------------|
| | | Page | Summary |
| 1.00 | Sep.29.03 | — | First edition issued |
| 2.00 | Sep.01.06 | 1, 3 | New addition and content correction |
| | | | |
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