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April 1<sup>st</sup>, 2010  
Renesas Electronics Corporation

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## H8S/2200 Series

### DMA Transfer of SCI Receive Data to SRAM

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#### Introduction

Data received from the serial interface (SCI) is transferred to the SRAM by using the DMAC.

#### Target Device

H8S/2215

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### 3. Description of Functions

The DMAC is started by inputting a command from the terminal software connected to the RS-232C interface. Moreover, a function for reading from and writing to memory and a function for reading from and writing to registers internal to the microcomputer are provided for debugging.

#### 1. Communication specifications

The terminal software is connected according to the specifications below.

Communication method	Asynchronous
Bit rate	38400 bps
Data size	8 bits
Parity	None
Stop bit	1 bit
Terminating code	Line feed

#### 2. Supported functions

No.	Function	Specifications
1	From the serial interface (SCI1), data as long as specified in length is transferred to a specified memory location by DMA.	Format: dm $\Delta$ address $\Delta$ length (Specify a 4-byte value in address, and a 2-byte value in length.)
2	Data of 64 bytes is read from a specified memory address for display.	Format: mr $\Delta$ address (Specify a 4-byte value in address.)
3	Data of 4 bytes is written starting at a specified memory address.	Format: mw $\Delta$ address $\Delta$ data (Specify a 4-byte value in address and data.)
4	A register internal to the H8S/2215 is read for display.	Format: hr $\Delta$ address (Specify a 2-byte value in address.) All registers are displayed if no value is specified in address.
5	Specified data is written to a register internal to the H8S/2215.	Format: hw $\Delta$ address $\Delta$ data (Specify a 4-byte value in address, and a 1-byte value in data.)

## 4. Principles of Operation

### 4.1 Initialization Processing

Before exercising DMAC control, start up the microcomputer and perform operations such as internal register initialization.

1. Control for low power consumption, clock oscillator initialization.

Register name	Bit	Name	Value	Contents
<b>←Set value</b>				
LPWCR	7-4	----	0000	
←0x03	3	RFCUT	0	Uses internal feedback resistance control.
	2	----	0	
	1:0	STC[1:0]	11	Bypasses PLL.
MSTPCRA	7	MSTPA7	0	Operates the DMAC module.
←0x0D	6	MSTPA6	0	Operates the DTC module.
	5	MSTPA5	0	Operates the TPU module.
	4	MSTPA4	0	Operates the TMR module.
	3:2	MSTPA[3:2]	11	(Reserved)
	1	MSTPA1	0	Operates the AD module.
	0	MSTPA0	1	(Reserved)
MSTPCRB	7	MSTPB7	0	Operates the SCI0 module.
←0x1F	6	MSTPB7	0	Operates the SCI1 module.
	5	MSTPB7	0	Operates the SCI2 module.
	4:1	MSTPB[4:1]	1111	(Reserved)
	0	MSTPB0	1	Stops the USB module.
	MSTPCRC	7:6	MSTPC[7:6]	11
←0xDF	5	MSTPC5	0	Operates the DA module.
	4:0	MSTPC[4:0]	11111	(Reserved)

2. I/O port initialization

Set the input/output pins of port G as indicated below. Set all other pins to the output mode.

Port	Register name ←Set value	Bit	Name	Value	Contents
G	PGDDR ←0xFF	7:5	---	11	
		4:2	PG[4:2]DDR	111	Output (Not used)
		1	PG1DDR	1	Output (CS3 enabled)
		0	PG0DDR	1	Output (Not used)

3. Bus controller initialization

Set the bus so that the externally connected SRAM (128k × 16 bits) can be accessed.

Register name ←Set value	Bit	Name	Value	Contents
ABWCR ←0x77	7	ABW7	0	Area 7 Bus width 16 bits (Not used)
	6:4	ABW[6:4]	111	Areas 6 to 4 Bus width 8 bits (Not used)
	3	ABW3	0	Area 3 Bus width 16 bits (SRAM)
	2:0	ABW[2:0]	111	Areas 2 to 0 Bus width 8 bits (Not used)
PFCR ←0x0F	7:4	----	0	
	3:0	AE[3:0]	1111	Enables A23:00 output.

4. TPU0 timer initialization

Make settings so that a timer interrupt is generated at intervals of 100 ms for timer monitoring.

Register name	Bit	Name	Value	Contents
<b>←Set value</b>				
TCR_0	7:5	CCLR[2:0]	001	Counter clear by TGRA compare match
←0x23	4:3	CKEG[1:0]	00	Count on rising edge
	2:0	TPSC[2:0]	011	Count with $\phi/64$
TMDR_0	7:6	----	00	
←0x00	5	BFB	0	Normal TGRB operation
	4	BFA	0	Normal TGRA operation
	3	----	00	
	2:0	MD[2:0]	000	Normal operation
TIORH_0	7:4	IOB[3:0]	0000	TBRB output compare (Not used)
←0x00	3:0	IOA[3:0]	0000	TBRA output compare
TIORL_0	7:4	IOD[3:0]	0000	TBRD output compare (Not used)
←0x00	3:0	IOC[3:0]	0000	TBRC output compare (Not used)
TIER_0	7	TTGE	0	Disables AD conversion start request. (Not used)
←0x00	6	----	0	
	5	TCIEU	0	Disables underflow interrupt. (Not used)
	4	TCIEV	0	Disables overflow interrupt. (Not used)
	3	TGIED	0	Disables TGRD interrupt. (Not used)
	2	TGIEC	0	Disables TGRC interrupt. (Not used)
	1	TGIEB	0	Disables TGRB interrupt. (Not used)
	0	TGIEA	0	Enables TGRA interrupt.
TGRA_0	15:0	TGRA_0	25000	TBRA output compare value
←25000				(To be set to generate an interrupt at intervals of 100 ms)
TCNT_0	15:0	TCNT_0	0x0000	Counter clear
←0x0000				
TSTR	7:0	TSTR	0x01	TCNT_0 counter start
←0x01				

5. Serial interface (SCI\_1) initialization

Make settings to connect the terminal software for starting the DMAC.

Register name	Bit	Name	Value	Contents
<b>←Set value</b>				
SCR_1 ←0x00	7	TIE	0	Disables transmit interrupt.
	6	RIE	0	Disables receive interrupt.
	5	TE	0	Disables transmit operation.
	4	RE	0	Disables receive operation.
	3	MPIE	0	Disables multi-processor interrupt.
	2	TEIE	0	Disables transmit end interrupt.
	1:0	CKE[1:0]	00	Asynchronous, internal clock used
	7	TIE	0	Disables transmit interrupt.
SMR_1 ←0x00	7	C/A	0	Asynchronous mode
	6	CHR	0	8-bit length
	5	PE	0	No parity check.
	4	O/E	0	Even parity (Not used)
	3	STOP	0	One stop bit
	2	MP	0	Disables the multi-processor communication function.
	1:0	CKS[1:0]	00	Clock source = $\phi$
	7:4	----	0000	
SCMR_1 ←0x00	3	DIR	0	LSB first
	2	INV	0	No data inversion
	1-0	----	00	
BRR ←12	7:0	BRR	12	Sets the transmission speed to 38400 bps.

— The time for at least one stop bit is awaited. (38400 bps: About 30  $\mu$ s)

— Receive processing is enabled.

Register name (Address←Set value)	Bit	Name	Value	Contents
SCR_1 ←0x50	7	TIE	0	Disables transmit interrupt.
	6	RIE	1	Enables receive interrupt.
	5	TE	0	Disables transmit operation.
	4	RE	1	Enables receive operation.
	3	MPIE	0	Disables multi-processor interrupt.
	2	TEIE	0	Disables transmit end interrupt
	1:0	CKE[1:0]	00	Asynchronous, internal clock used

## 4.2 DMAC Control

### 1. Overview

The DMAC is started by a command from the terminal software connected to SCI\_1.

Format: dmAddressAlength (Specify a 4-byte value in address, and 2-byte value in length.)

As many data characters as specified in length received from the serial interface (SCI1) are transferred by DMA to the memory specified in address. In this application note, a setting is made so that no normal receive interrupt is generated during DMA transfer by resetting a receive interrupt source with the DMAC (depending on the setting of DMABCRH (DTA0A)). Upon completion of transfer of data characters as many as specified in length, a DMAC end interrupt is generated to end DMA transfer processing.

The DMAC of the H8S/2215 has four channels (0A, 0B, 1A, and 1B) and operates in the operating modes indicated below. In this application note, channel 0A is used in the sequential mode of the short address mode. For the detailed specifications of each operating mode, refer to the "H8S/2215 Series Hardware Manual."

Transfer mode		Transfer source	Remarks
Short address mode	Dual address mode	(1) <u>Sequential mode</u>	<ul style="list-style-type: none"> <li>Up to 4 channels can be operated independently of each other.</li> </ul>
		(2) Idle mode	
		(3) Repeat mode	
Full address mode	(4) Normal mode	<ul style="list-style-type: none"> <li>USB request</li> <li>Auto-request</li> </ul>	<ul style="list-style-type: none"> <li>Up to 2 channels combining channels A and B can be operated.</li> <li>In the case of an auto-request, a choice can be made between burst mode transfer and cycle steal transfer.</li> </ul>
	(5) Block transfer mode	<ul style="list-style-type: none"> <li>Compare match/input capture A interrupt of the TPU channels 0 to 2</li> <li>SCI send data empty interrupt</li> <li>SCI receive data full interrupt</li> <li>A/D converter conversion end interrupt</li> <li>USB request</li> </ul>	

2. DMAC setting

Before starting the DMAC, set each register of channel 0A according to the procedure below.

This application program enables this setting to be made using one subroutine (dma\_rxd\_to\_ram) at a time. For details, see section 5, "Description of Sample Program."

No.	Setting	Register to be set
1	Sets the operating mode to the short address mode	DMABCRH (FAE0) ←0
2	Sets for resetting a receive interrupt source with the DMAC during DMA transfer	DMABCRH (DTA0A) ←1
3	Sets of a transfer source address (RDR_1: Receive data storage area of SCI1) in IOAR0A	IOAR0A←FF85
4	Sets of a transfer destination address in MAR0A	MAR0A←address (Lower 3 bytes of address received with a command)
5	Sets of the number of transfers in ETCR0A	ETCR0A←length (Lower 2 bytes of length received with a command)
6	Sets of 1 byte as the unit of DMA transfer	DMCRA (DTSZ) ←0
	Incrementing MAR0A by 1 each time a DMA transfer is made	DMCRA (DTID) ←0
	Sets of the sequential mode	DMCRA (RPE) ←0
	Sets of IOAR as a transfer source, and MAR as a transfer destination	DMCRA (DTPDIR) ←0
	Sets for starting DMA with a receive data full interrupt of SCI channel 1	DMCRA (DTF[3:0]) ←7
7	Sets for enabling DMA data transfer (Actual transfer processing is performed when an SCI1 receive interrupt is generated.)	DMABCRH (DTE0A) ←1 (Unless the state of DTE0A=0 is read beforehand, 1 cannot be set.)
8	Sets for generating a DMA end interrupt of channel 0A when DMA transfer ends	DMABCRH (DTIE0A) ←1

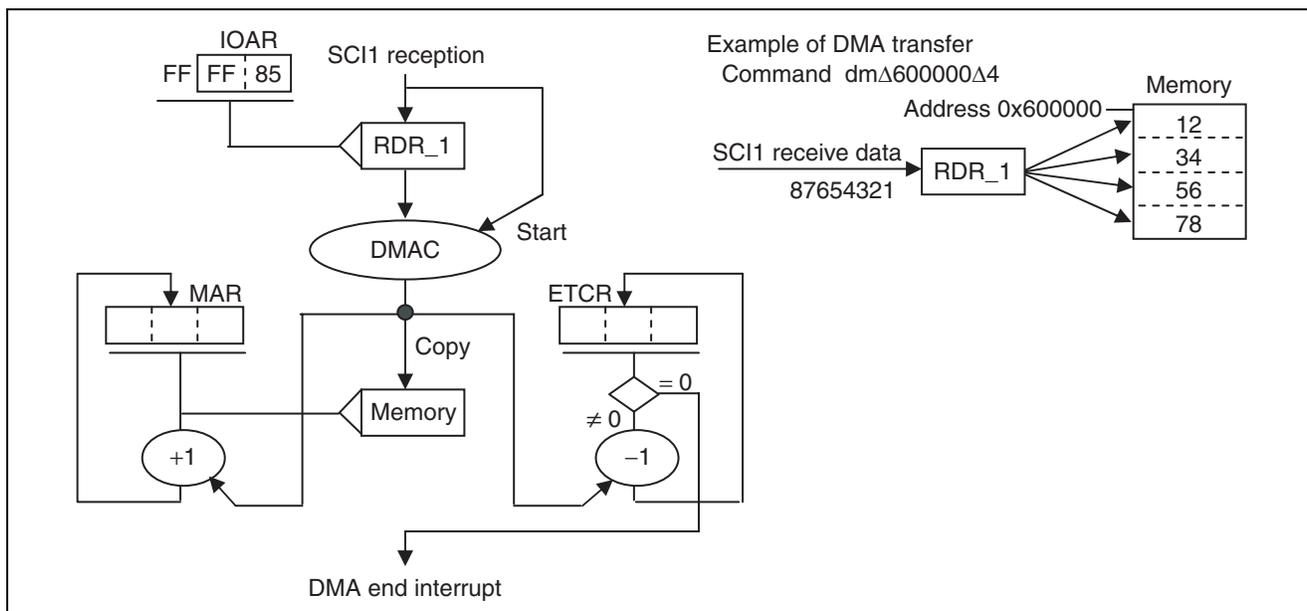
### 3. DMAC operation

If the settings above have been made, a DMA transfer is made each time SCI1 data is received.

DMA transfers are made as many times as the number of transfers set in the ETCR0A register. An end interrupt of DMAC channel 0A is finally generated to end the processing.

The processing flow of this operation is described below.

- A. When SCI1 receive data is stored in the RDR\_1 register, the DMAC is started.
- B. The DMAC copies the data of the transfer source address (RDR\_1 address) indicated by the IOAR0A register to the transfer destination address indicated by the MAR0A register. At this time, an SCI1 receive interrupt source is reset by the DMAC.
- C. The DMAC increments the transfer destination address indicated by the MAR0A register by 1, and decrements the number of transfers indicated by the ETCR0A register by 1.
- D. Steps A. to C. are repeated until ERCT0A is cleared to 0.
- E. When ERCT0A is cleared to 0, a DMA end interrupt of DMAC channel 0A is generated, and the DMAC resets DMABCRH (DTE0A) to 0.
- F. During DMA end interrupt processing, the software clears DMABCRH (DTIE0A) to 0 to end DMAC processing.



## 5. Description of Sample Program

### 5.1 File Configuration

A sample program is provided as a project of HEW (High-performance Embedded Workshop). When h8s.hws is executed, HEW starts up to enable source program referencing and updating. If you do not have HEW, directly reference the following source files with an editor:

No.	File name	Application
1	resetprg.c	Executed starting at reset vector address 0 when the microcomputer is reset
2	intprg.c	Executed when an interrupt source other than a reset is generated
3	dbstc.c	Processing for setting the start and end addresses of a section used by the _INITSCT function of resetprg.c in the section initialization table. For details of the processing, refer to sections 9 and 10 of the "H8S and H8/300 Series C/C++ Compiler, Assembler, Optimizing Linkage Editor User's Manual."
4	h8s.c	Main routine of this application note
5	com.c	Main common and interrupt processing routine of this application note
6	2215S.H	Structure definition file of the internal registers of the H8S/2215 This file can be obtained from * <sup>2</sup> . However, modifications are made to the DMAC-related definition. For the modifications, check the source code.
7	cwtbl.h	Variable and constant definitions are made for this application note.
8	prototypeh	A prototype declaration is made for this application note.
9	stacksct.h	A stack size definition is made.

\*<sup>1</sup> <http://www.renesas.com/>

\*<sup>2</sup> <http://www.renesas.com/>

### 5.2 Linkage

The linkage address of each section is indicated below.

In a HEW project file, a section can be referenced or set with Category : section in the Link/Librarq tab of the - Standard Toolchain option.

Section	Start address
PRresetPRG	0x000400
PIntPRG	
P	0x000800
C	
C\$DSEC	
C\$BSEC	
D	
B	0xFFB000
R	
S	0xFFEDB0

### 5.3 Subroutine Specifications

With this application note, DMA parameters can be set and started using one subroutine. This function eases the use of DMA.

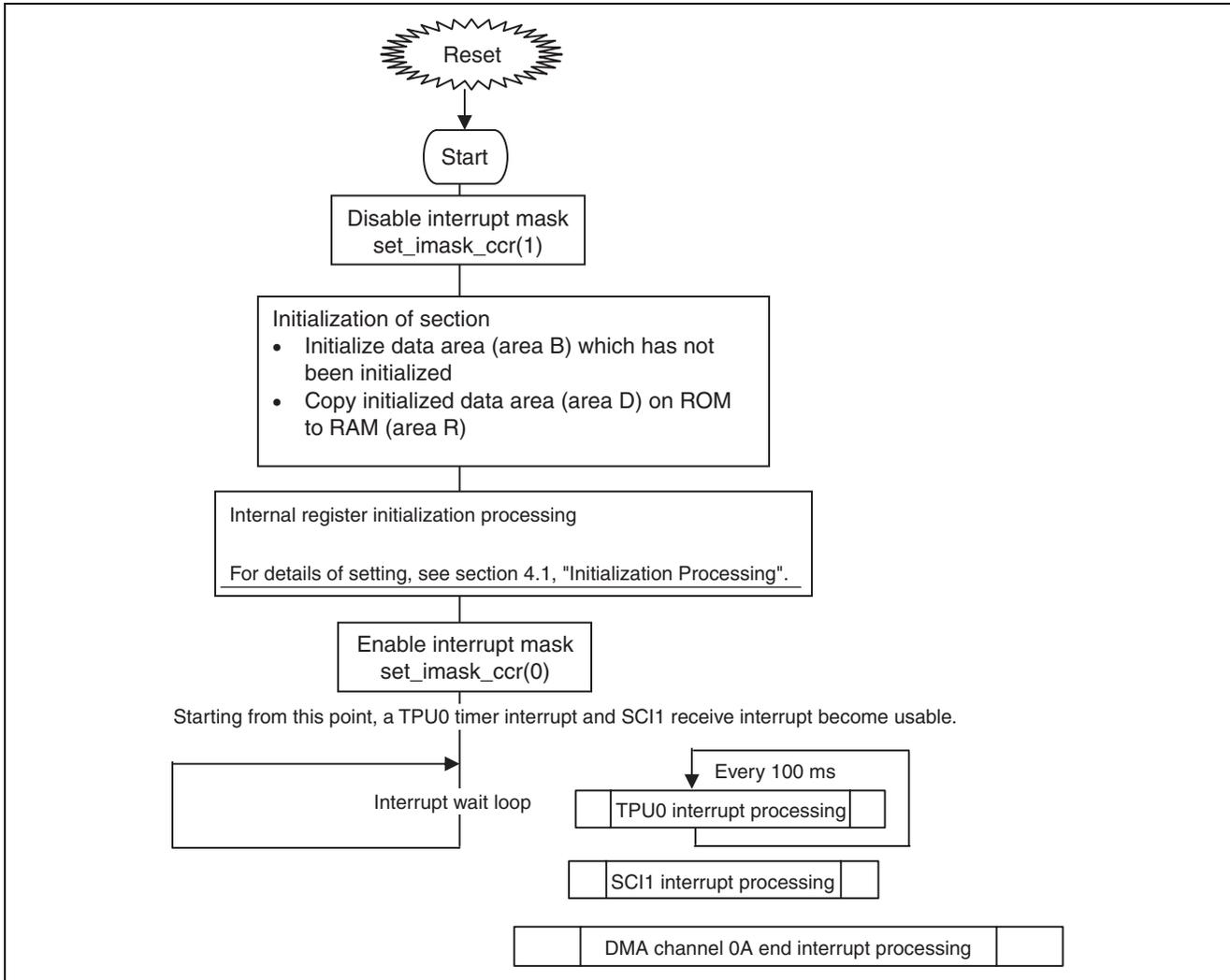
1. Data received from SCI is transferred by DMA to a specified address.

```
Subroutine name: void dma_rxd_to_ram
                 ( int sci_no , unsigned long ram_addr , unsigned int length)
```

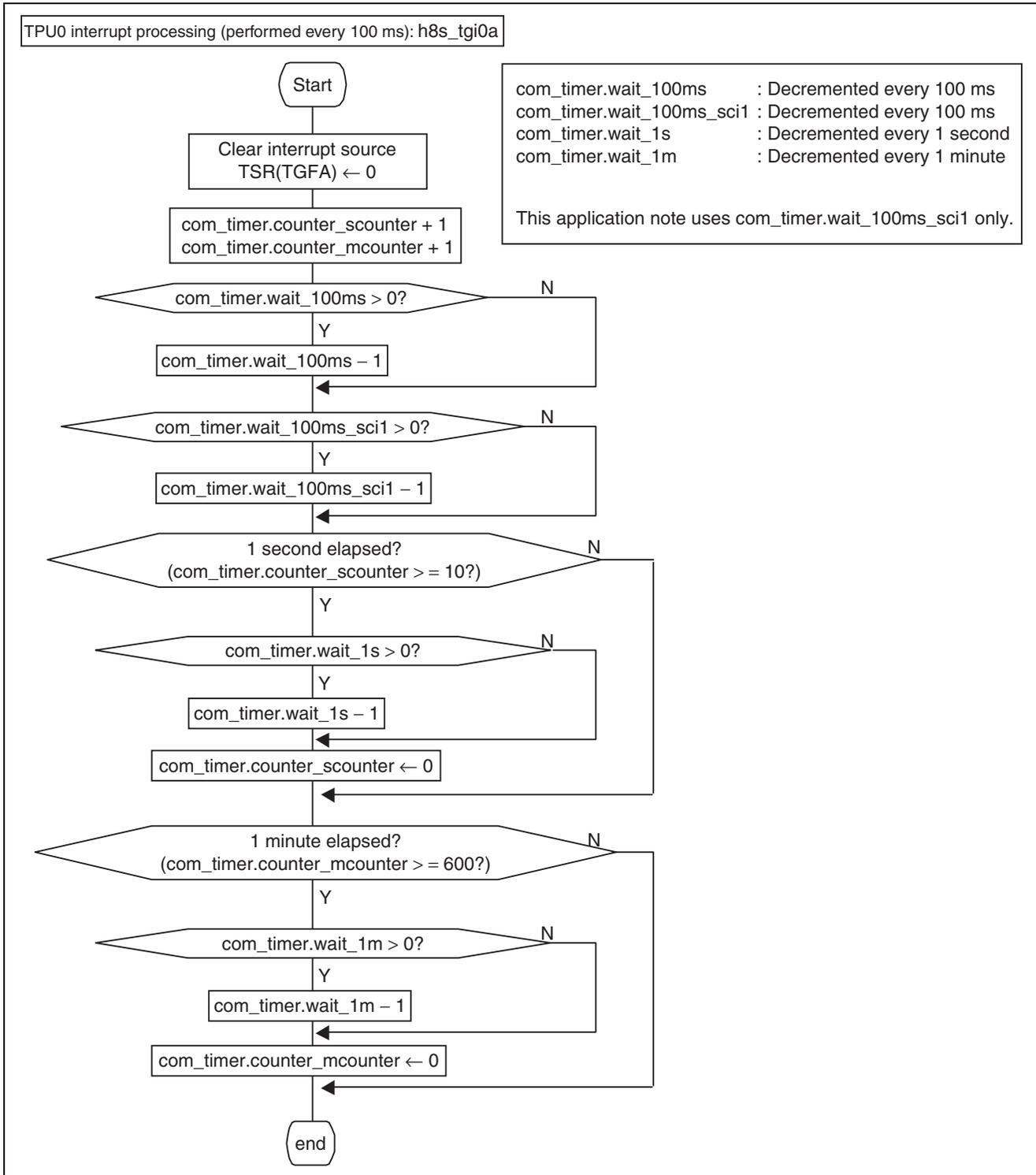
Argument	Setting
sci_no	Specifies an SCI number. <b>SCI_0</b> (0) : SCI_0 <b>SCI_1</b> (1) : SCI_1 With the H8S/2215, SCI_2 cannot be used as a DMA start source, so that SCI_2 may not be specified here.
ram_address	Specifies the start address of an area where data received from the SCI is to be stored.
length	Specifies the size of data to be transferred by DMA. When data of a specified size has been transferred, a DMA end interrupt is generated.

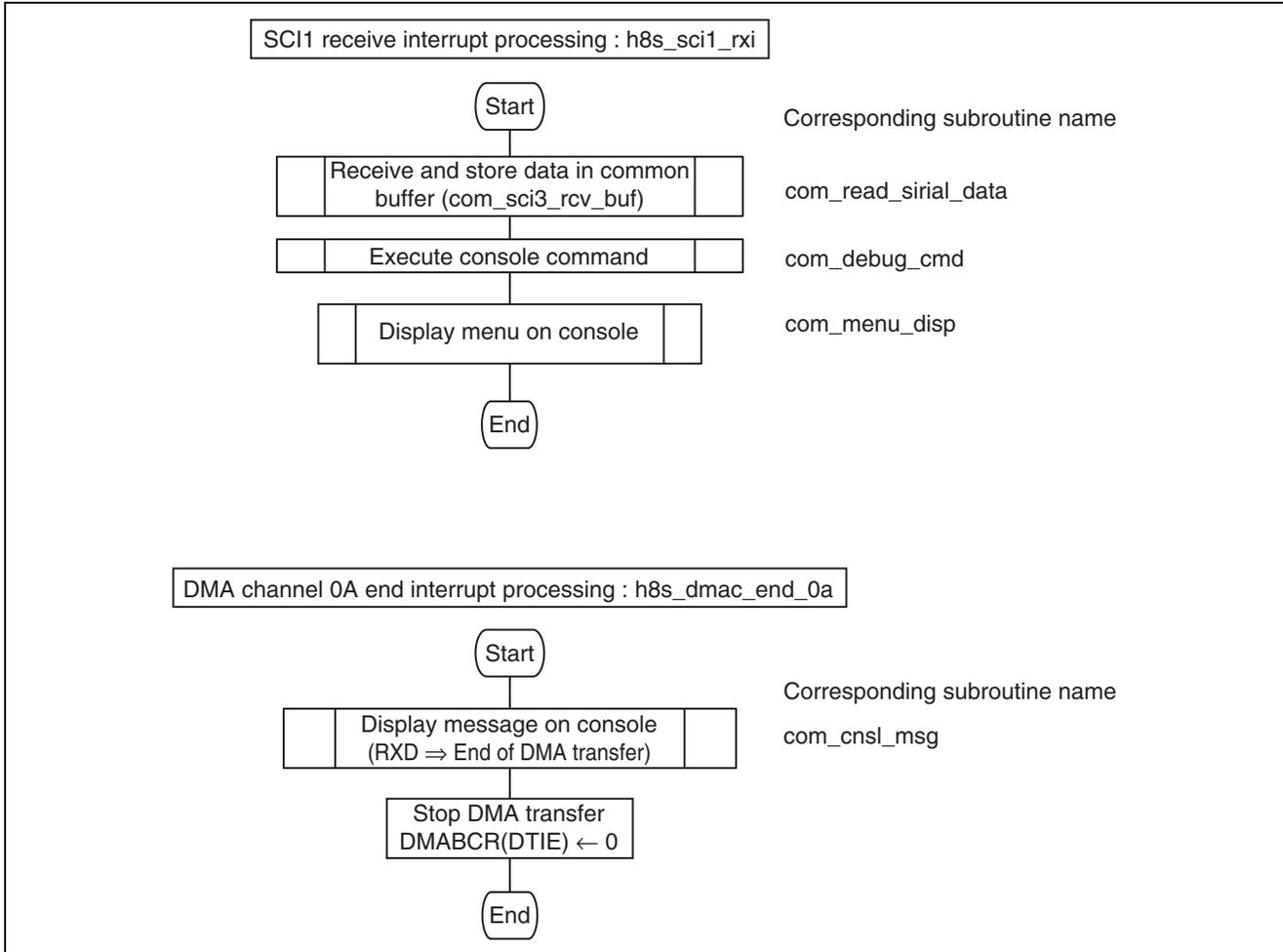
6. Flowchart

6.1 Overall flow



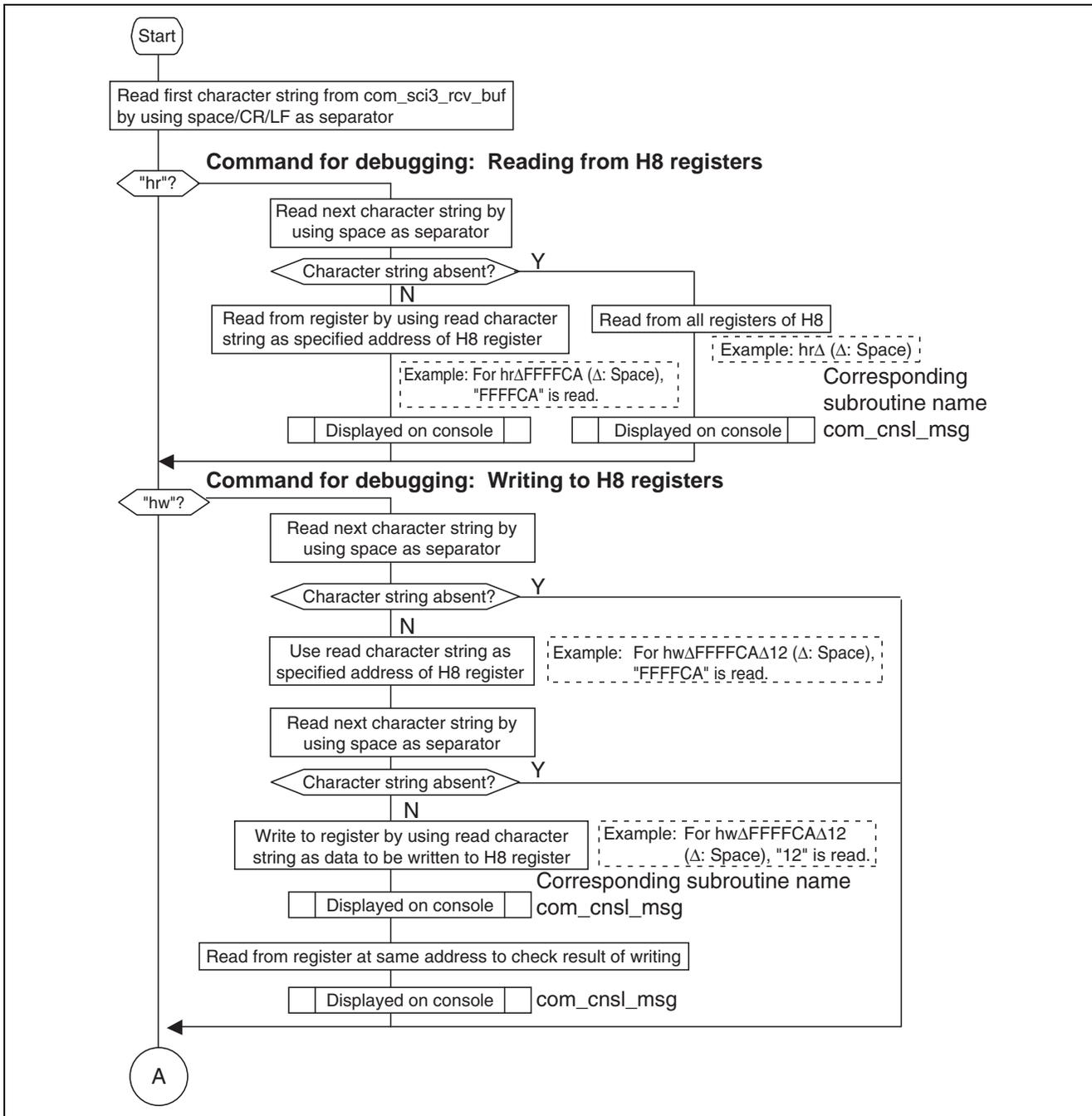
6.2 Interrupt processing

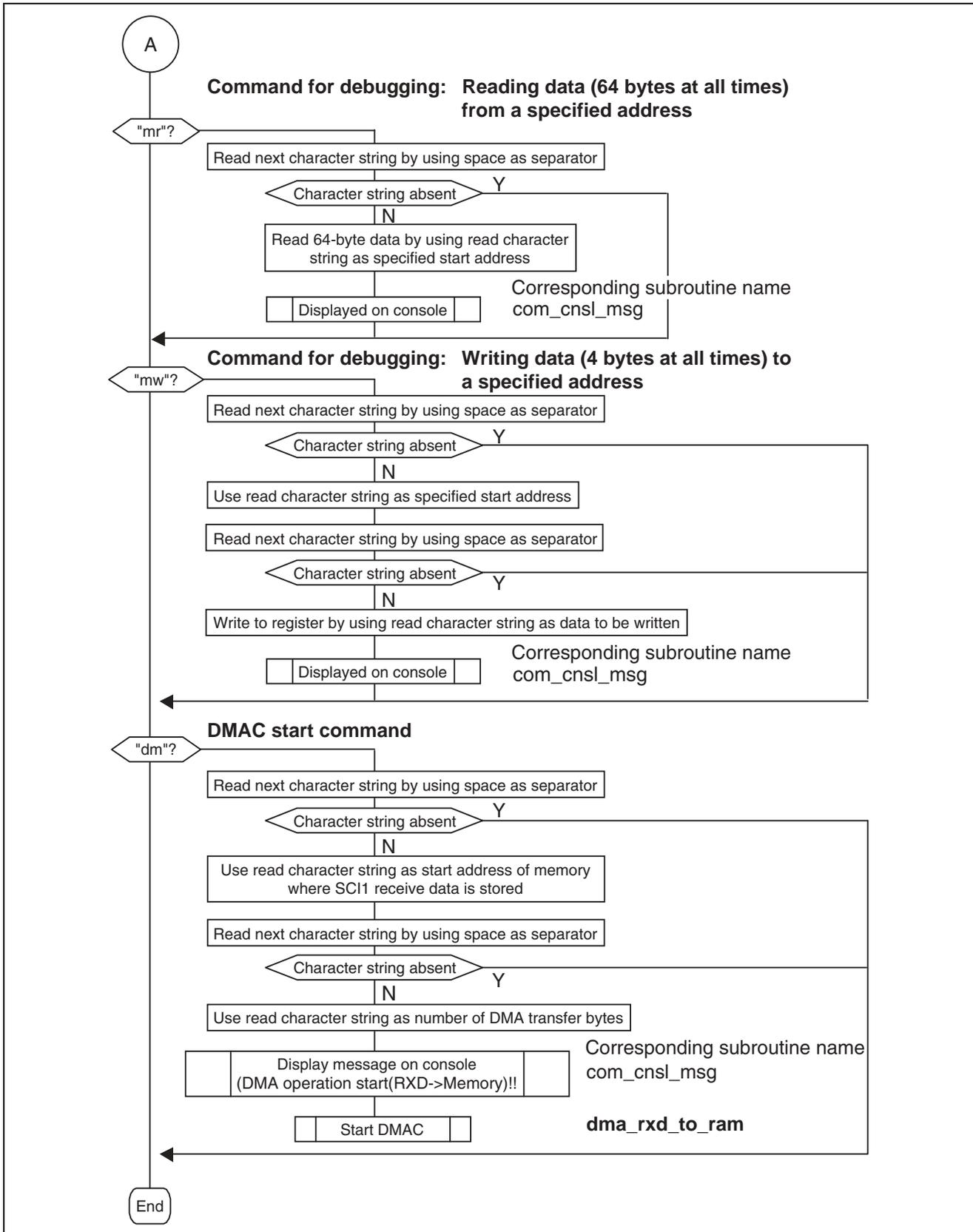




### 6.3 Detailed processing

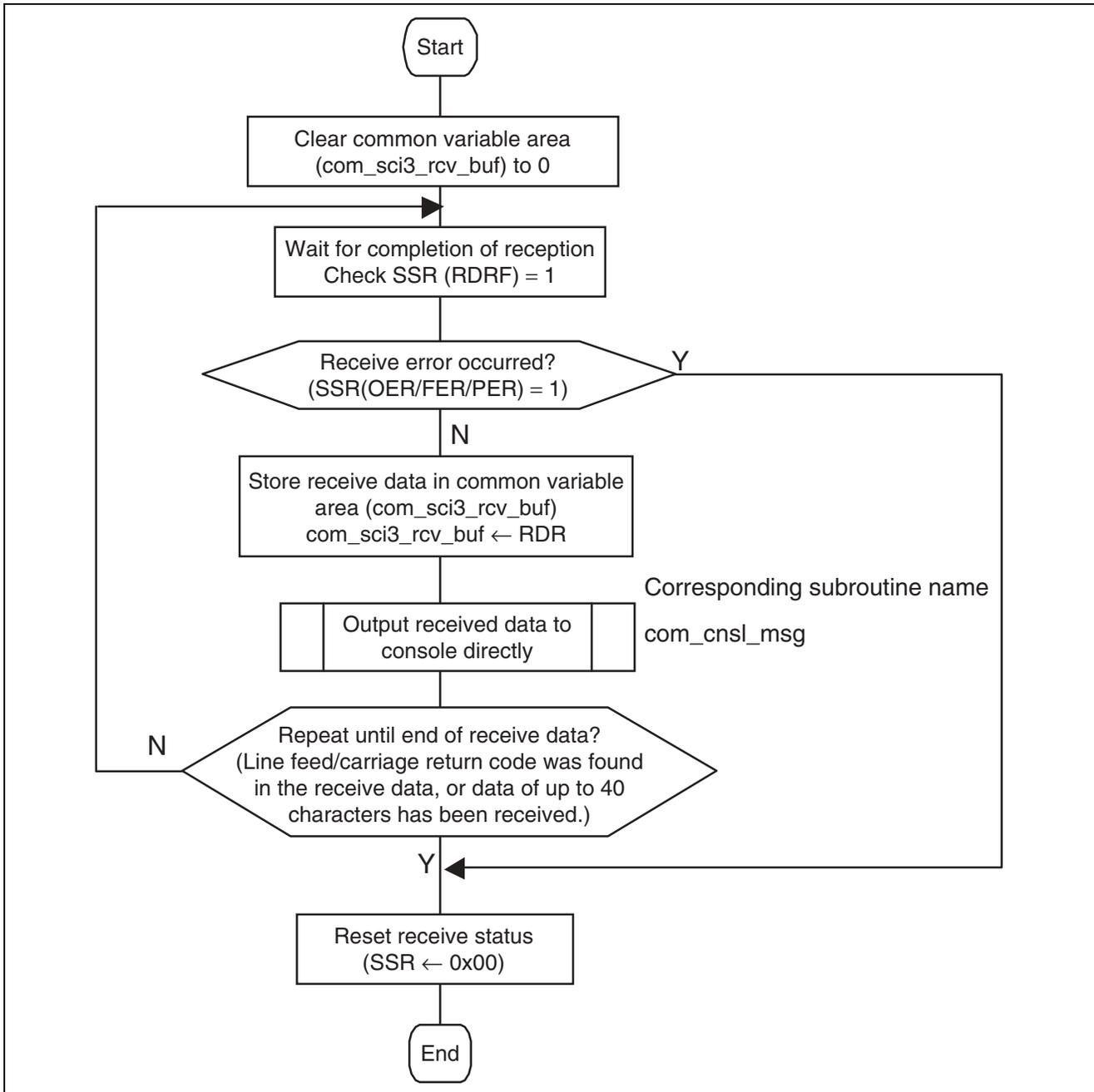
com\_debug\_cmd  
: Console command analysis and execution





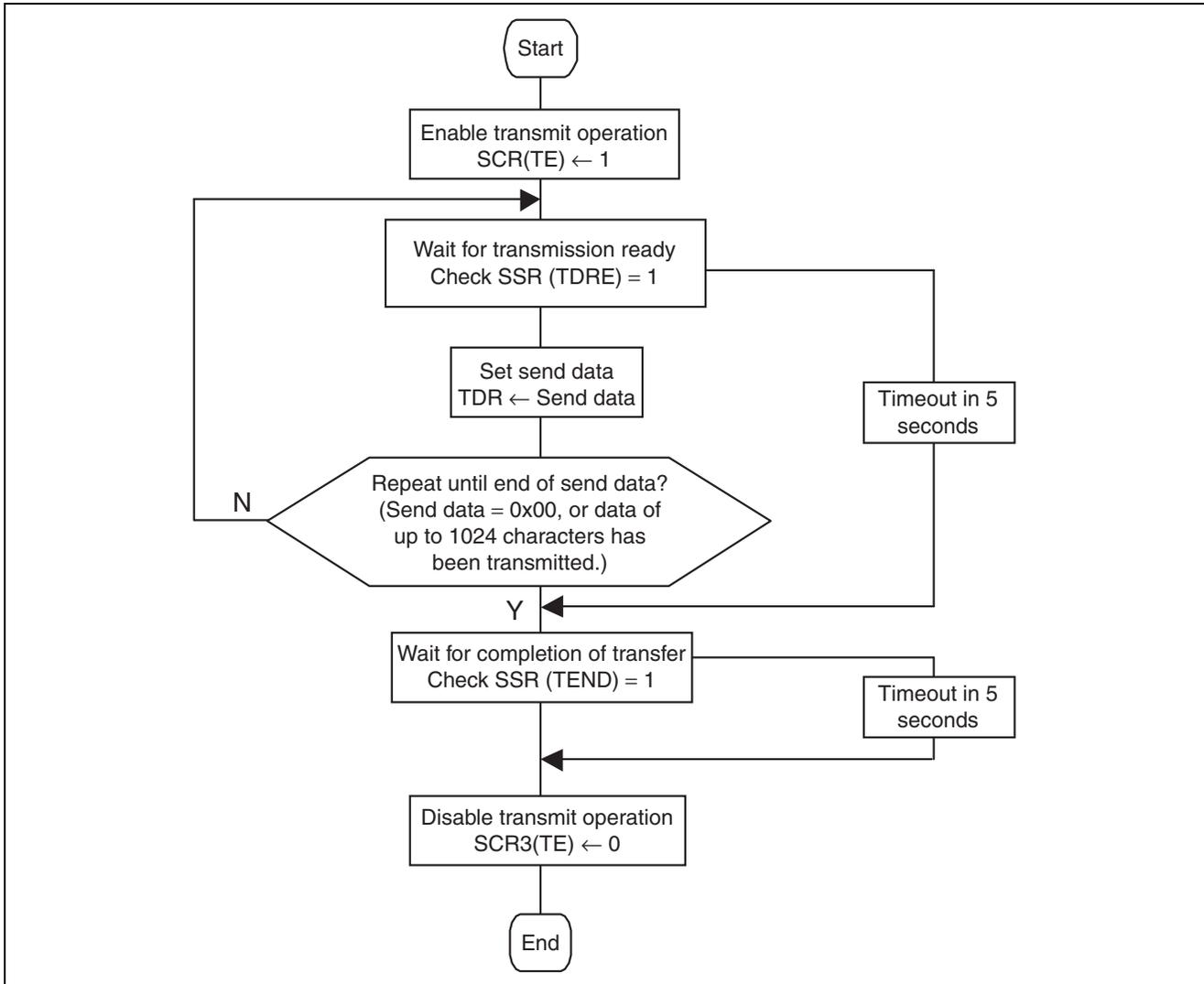
com\_read\_sirial\_data

: Reception of a message from the SCI1 interface  
 Receive data not longer than 40 characters is received  
 in the common variable area (com\_sci3\_rcv\_buf).

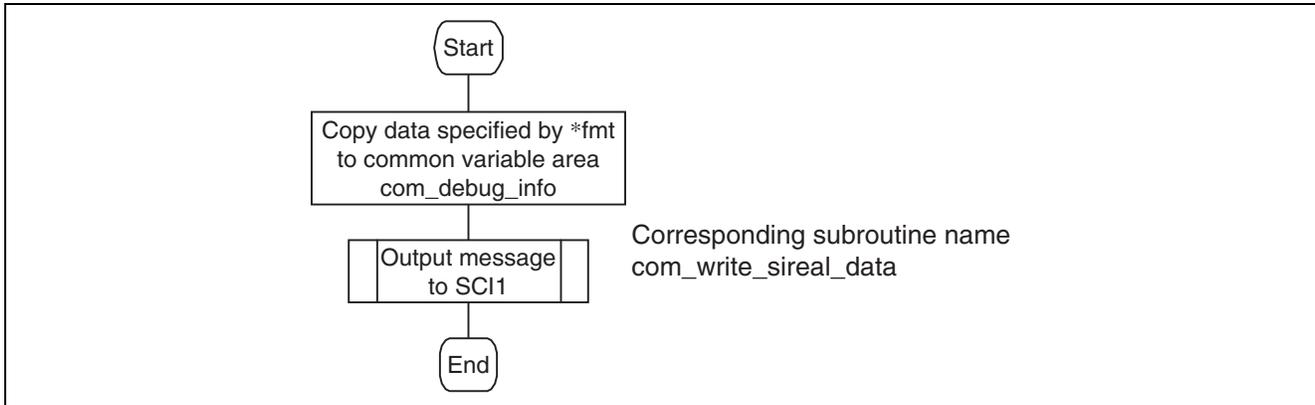


```

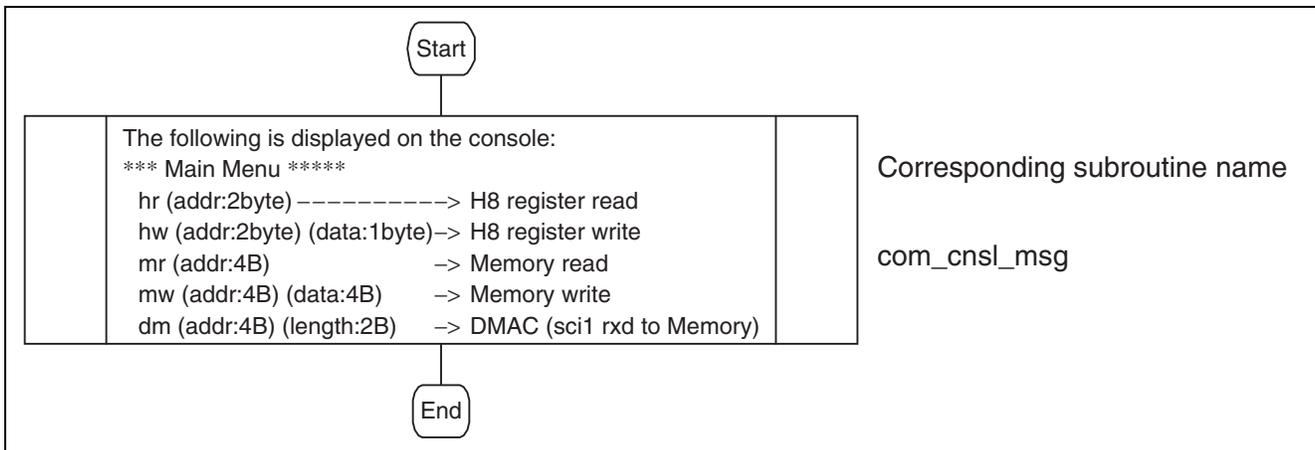
com_write_sireal_data ( char *p )
: Transmission of a message to the SCI3 interface
  *p : Address where message data is stored
    
```



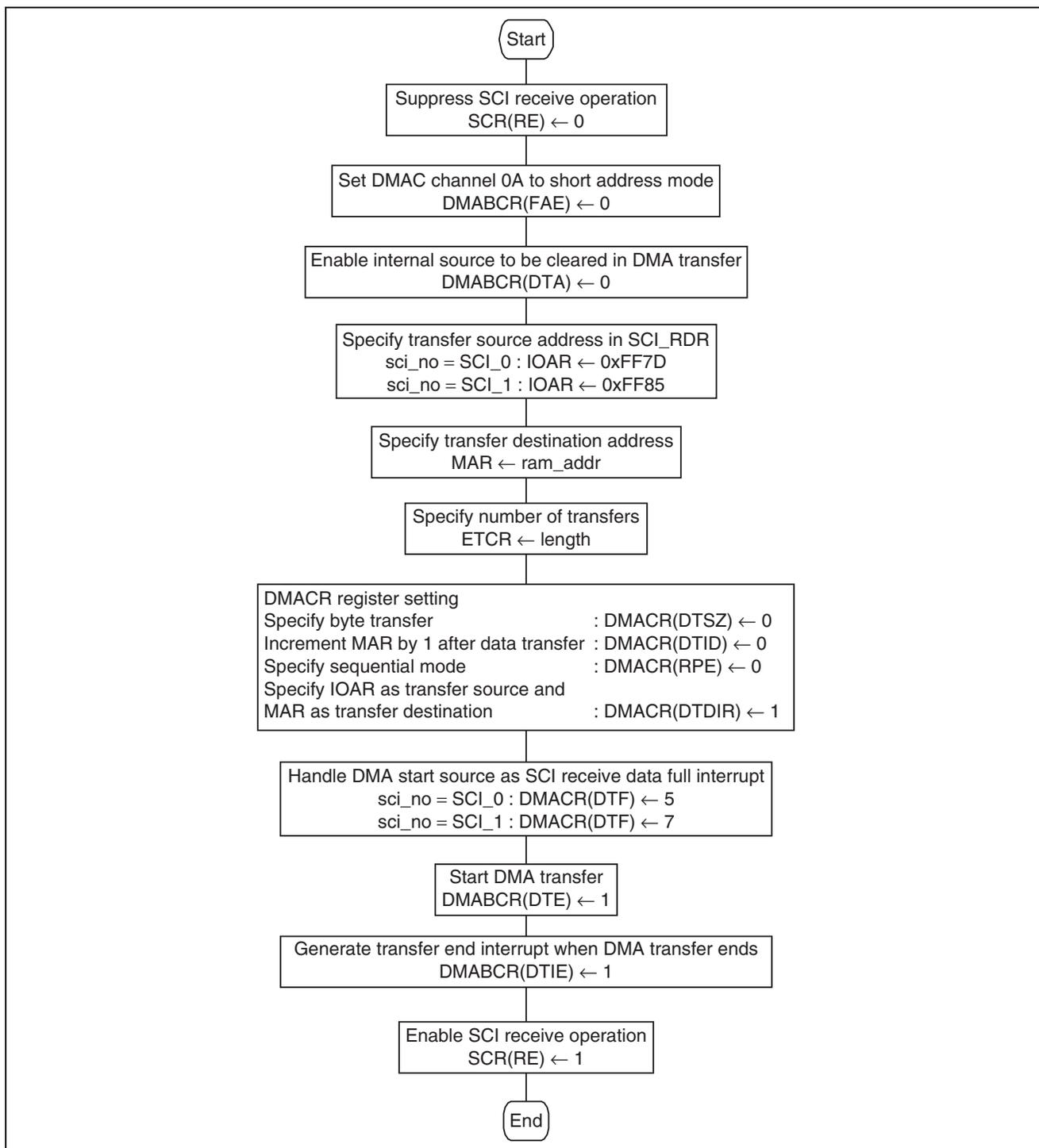
```
com_cns1_msg(char *fmt, ...)
: Transmission of a message to the console
  *fmt : Address where variable-length message data is stored
```



```
com_menu_disp
: Display of the operation menu on the console
```



dma\_rxd\_to\_ram ( int sci\_no , unsigned long ram\_addr , unsigned int length)  
 : DMA transfer of SCI1 receive data to a specified address  
 sci\_no : Specifies an SCI number (SCI\_0 or SCI\_1).  
 ram\_addr : Specifies the start address of an area where SCI receive data is stored.  
 length : Specifies the size of data to be transferred by DMA.



**Revision Record**

Rev.	Date	Description	
		Page	Summary
1.00	Mar.16.04	—	First edition issued

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