

R8C/35A, R8C/35C, R8C/35D, R8C/35M Groups

Differences between R8C/35A, R8C/35C, R8C/35D, and R8C/35M Groups

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1. Abstract

This document is reference material for identifying differences between the R8C/35A Group, R8C/35C Group, R8C/35D Group, and R8C/35M Group.

2. Introduction

This document applies to the following microcomputers (MCUs):

• MCUs: R8C/35A Group, R8C/35C Group, R8C/35D Group, R8C/35M Group

3. Differences between Groups

3.1 Function and Specification Differences

Table 3.1 and Table 3.2 list differences in the functions and specifications. For more details and electrical characteristics, refer to the documents listed in 5. Reference Documents.

Table 3.1 Function and Specification Differences (1)

	~~~ <del>!</del>	200 V 301 Oct	200000	Since O Mac/ Oct	20000
	Item	R&C/35A Group	R8C/33C Group	R&C/35M Group	R&C/35D Group
Memory	ROM/RAM	• 16 KB/1.5 KB • 24 KB/2 KB • 32 KB/2.5 KB • 48 KB/4 KB • 64 KB/6 KB • 96 KB/8 KB			• 16 KB/1 KB • 24 KB/1 KB • 32 KB/1 KB
Voltage Detection Circuit	Voltage Detection Circuit Voltage detection 2	Detection voltage can be selected. (VCC or LVCMP2 pin)	Detection voltage cannot be selected.	Detection voltage can be selected. (VCC or LVCMP2 pin)	Detection voltage cannot be selected.
Bus Control		Registers DA0, DA1, RMAD0 by an 16-bit bus.	Registers DA0, DA1, RMAD0, AIER0, RMAD1, and AIER1 are connected to the CPU by an 16-bit bus.	are connected to the CPU	Registers RMAD0, RMAD1, and AIER are connected to the CPU by an 8-bit bus.
Clock Generation Circuit	Peripheral function clock	fC2 is included in the peripheral function clock.	ral function clock.		fC2 is not included in the peripheral function clock.
High-Speed On-Chip Oscillato	Chip Oscillator	Not included (1)	Included (2)		
	Select 10b for bits CM37 and CM36	Not available	Available	Not available	Available
Power Control	• Enter stop mode while bits CM37 and CM36 are 00b in high-speed onchip oscillator mode	I	Available	Not available	Available
	• Select 11b for bits CM37 and CM36 in low-speed clock mode.	Available		Not available	Available
Interrupts		Number of interrupt     Sources: 40     External interrupt inputs: 9 • External interrupt input x 4) (INT x 5 and key input x 4)	of interrupt errupt inputs: 9 d key input x 4)	• Number of interrupt • Number of interrupt • Sources: 36 • External interrupt inputs: 9 • External int (INT x 5 and key input x 4)	• Number of interrupt sources: 30 • External interrupt inputs: 9 (INT x 5 and key input x 4)
DTC		Included			Not included
Timer RD		Included			Not included
Notes:					

Notes

Since the R8C/35A Group does not include a high-speed on-chip oscillator, it cannot be selected as the peripheral function count source. Electrial characteristics for the high-speed on-chip oscillator in these groups differ. Refer to the documents of each group for details.

Table 3.2 Function and Specification Differences (2)

	Item	R8C/35A Group	R8C/35C Group	R8C/35M Group	R8C/35D Group
	UART1	lncluded	-	-	Not included
Serial Interface	td(C-Q) TXDi output delay time	Maximum 70 ns (VCC = 5.0 V)	Maximum 50 ns (VCC = 5.0 V)	When selecting external clock: Maximum 90 ns (VCC = 5.0 V)     When selecting internal clock: Maximum 10 ns (VCC = 5.0 V)	Maximum 50 ns (VCC = 5.0 V)
Synchronous Serial Communication Unit (SSU)	ial Jnit (SSU)	Included			Not included
I ² C-bus Interface		Included			Not included
Hardware LIN		Included			Not included
	Conversion rate per pin ( $\phi$ AD = fAD)	Minimum: 43 ¢AD cycles	Minimum: 44 ¢AD cycles		
A/D Converter	Sampling time	15 φAD (φAD = 20 MHz: 0.75 μs)	16 φAD (φAD = 20 MHz: 0.8 μs)		
	A/D conversion execution time	Open-circuit detection disabled: 40 ¢AD cycles Open-circuit detection enabled: 42 ¢AD cycles	Open-circuit detection disable Open-circuit detection enable	Open-circuit detection disabled: 40 ¢AD cycles + 1 to 3 fAD cycles Open-circuit detection enabled: 42 ¢AD cycles + 1 to 3 fAD cycles	) cycles ) cycles
D/A Converter		Included			Not included
Comparator A		Included	Not included	Included	Not included
	Program operation (programming to the flash memory) while auto-erasure is suspended for the suspend function.	Cannot be performed	Can be performed		
Flash Memory	Interval from erase start/restart until following suspend request	Minimum: 33 ms	Minimum: 0 ms		
	Suspend interval necessary for auto-erasure to be completed	Minimum: 33 ms	Minimum: 0 ms		
	Data flash (including BGO)	Included			Not included

#### 3.2 **Pin Function Differences**

Table 3.3 lists differences in the I/O ports assigned to the peripheral function pins. For more details, refer to the documents listed in 5. Reference Documents.

Table 3.3 **Pin Function Differences** 

Peripheral Function Pin		Assigned	Assigned I/O Ports		
	R8C/35A Group	R8C/35C Group	R8C/35M Group	R8C/35D Group	
LVCMP1	P1_0	I	P1_0	I	
LVCMP2	P1_1	I	P1_1	I	,
LVREF	P1_2	I	P1_2	I	
LVCOUT1	P1_3	I	P1_3	I	
LVCOUT2	P1_6	I	P1_6	I	
CLK1		P6_5, P6_2, P0_3		I	
RXD1		P6_4, P0_2		I	
TXD1		P6_3, P0_1		I	
TRDIOA0		P2_0		I	
TRDIOB0		P2_2		I	
TRDIOCO		P2_1		I	
TRDIOD0		P2_3		I	
TRDIOA1		P2_4		I	
TRDIOB1		P2_5		I	
TRDIOC1		P2_6		I	
TRDIOD1		P2_7		I	
TRDCLK		P2_0		I	
SCL		P3_5		I	,
SDA		P3_7		I	
ISS		P3_4		I	
SCS		P3_3		I	,
SSCK		P3_5		I	
OSS		P3_7		I	
DA0		P0_6		I	
DA1		P0_7		I	
he symbol "—" indicates the	he symbol "—" indicates there is no pin for the peripheral function.	al function.			

## 3.3 Differences of SFRs

Table 3.4 to Table 3.6 list differences in the SFRs. For more details, refer to the documents listed in 5. Reference Documents.

Table 3.4 Differences of SFRs (1)

				3910	Difference to D8C/3EA Crous (1)	5
R8C/35A Group	R8C/35C Group	R8C/35M Group	R8C/35D Group	R8C/35C Group	R8C/35M Group	(1) R8C/35D Group
CMPA	CMPA	CMPA	CMPA	Bits 0 to 3 deleted	<u>-</u>	Bits 0 to 3 deleted
VCA2	VCA2	VCA2	VCA2	Bits 1 to 4 deleted     Functions changed in bits		Bits 1 to 4 deleted     Functions changed in bits
				6 and 7		6 and 7
VW2C	VW2C	VW2C	VW2C	Function changed in bit 7		Function changed in bit 7
	TRDPSR0		I			
	TRDPSR1		1			1
	U1SR		I			1
	SSUIICSR					I
	PINSR		PINSR			Bits 4 to 7 deleted
CM3	CM3	CM3	CM3	Functions changed in bits 6 and 7		Functions changed in bits 6 and 7
FRA0		FRA0		Functions added to bits 0, 1, and 3	8	
		FRA1		Register added		
		FRA2		Register added		
ı		FRA3		Register added		
I		FRA4		Register added		
I		FRA5		Register added		
I		FRA6		Register added		
I		FRA7		Register added		
	S1TIC					
	S1RIC		I			1
	TRD0IC		1			1
	TRD1IC		I			1
	SSUIC/IICIC		_			
	AIERO		AIER			<ul> <li>Register name changed</li> <li>Bit 1 added</li> </ul>
	AIER1		I			1
	DTCTL		-			1
	DTCEN0		I			1
	DTCEN1		_			
DTCEN2	DTCEN2	DTCEN2	I	Functions in bits 4 and 5 changed		ı
ni "—" lodmys ed-	he symbol "—" indicates there is no SEB	SFR				

The symbol "—" indicates there is no SFR.

Blank spaces indicate no difference with the R8C/35A Group.

Table 3.5 Differences of SFRs (2)

_					1		1	ı		1	1		1			1			1	1	1	ı									1			1
	R8C/35D Group	_	1	1	ı	I	1	Bit 3 deleted	Bits 3 and 4 deleted		1	Ţ	I	1	1	1	_	1	1	1	1	I	_	1	_	_	1	1	Ţ	1	1	1	Ţ	_
Differences to R8C/35A Group (1)	R8C/35M Group									9												2											2	
	R8C/35C Group									Functions changed in bits 4 to 6												Functions changed in bits 0 to 2											Functions changed in bits 0 to 2	
D8C/35D Group	droin according	_	I	_	I	_	I	TRAIOC	MSTCR		I	_	I	_	_	I	_	_	I	I	I	I	_	_	_	_	_	_	_	_	I	_	_	-
D8C/35M Group	dro o Miccoon					(				TRCCR1												TRDCR0											TRDCR1	
D8C/35C Group		DTCEN3	DTCEN4	DTCEN5	DTCEN6	DTCVCT0 to 63 (2)	DTCD0 to 23	TRAIOC	MSTCR		TRDECR	TRDADCR	TRDSTR	TRDMR	TRDPMR	TRDFCR	TRDOER1	TRDOER2	TRDOCR	TRDDF0	TRDDF1	TRE	TRDIORA0	TRDIORC0	TRDSR0	TRDIER0	TRDPOCR0	TRD0	TRDGRA0	TRDGRB0	TRDGRC0	TRDGRD0	TRD	TRDIORA1
D8C/35A Group	2500									TRCCR1												TRDCR0											TRDCR1	

Blank spaces indicate no difference with the R8C/35A Group. DTC transfer vector area (2C00h to 2C3Fh) The symbol "—" indicates there is no SFR.

Note:

1. Blank spaces indicate no difference
2. DTC transfer vertor area months.

Table 3.6 Differences of SFRs (3)

	2000				Differences to R8C/35A Group (1)	up (1)
dnois Acc/oox	Roc/sac Group	Roc/Solvi Group	Rec/33D Gloup	R8C/35C Group	R8C/35M Group	R8C/35D Group
	TRDIORC1		_			_
	TRDSR1		_			1
	TRDIER1		I			I
	TRDPOCR1		I			ı
	TRD1		I			ı
	TRDGRA1		I			ı
	TRDGRB1		I			ı
	TRDGRC1		I			ı
	TRDGRD1		I			ı
	U1MR		I			ı
	U1BRG		I			ı
	U1TB		I			I
	U1C0		I			I
	U1C1		I			I
	U1RB		I			I
	LINCR2		I			I
	LINCR		I			I
	LINST		I			ı
	SSBR		I			ı
	SSTDR/ICDRT		I			ı
	SSTDRH		I			ı
	SSRDR/ICDRR		I			ı
	SSRDRH		I			ı
	SSCRH/ICCR1		I			I
	SSCRL/ICCR2		I			I
	SSMR/ICMR		1			I
	SSER/ICIER		1			I
	SSSR/ICSR		I			I
	SSMR2/SAR		I			I
ADMOD	ADMOD	4OD	ADMOD	Function changed in bit 2		Functions changed in bits 2, 6, and 7
	DA0		-			_
	DA1		_			_
	DACON		1			I
	FMR1		FMR1			Bits 4 to 7 deleted
ir "—" loduns ad	he symbol "—" indicates there is no SER	2 SFR				

The symbol "—" indicates there is no SFR. Note:

1. Blank spaces indicate no difference

Blank spaces indicate no difference with the R8C/35A Group.

## 3.4 Interrupt Vector Differences

Table 3.7 lists differences in the fixed vector table and lists differences in the relocatable vector table. For more details, refer to the documents listed in 5. Reference Documents.

Table 3.7 Differences in Fixed Vector Table and Relocatable Vector Table

	of o							
	Interrupt Source of R8C/35D Group	I	I	I	I	I	Voltage monitor 1	Voltage monitor 2
	Interrupt Source of R8C/35M Group						Volage monitor 1/comparator A1 Voltage monitor 1	Volage monitor 2/comparator A2 Voltage monitor 2
	Interrupt Source of R8C/35C Group			n Unit/I2C-bus interface			Voltage monitor 1	Voltage monitor 2
locatable Vector Table	Interrupt Source of R8C/35A Group	Timer RD0	Timer RD1	Synchronous Serial Communication Unit/I2C-bus interface	UART1 transmit	UART1 receive	Volage monitor 1/comparator A1 Voltage monitor 1	Volage monitor 2/comparator A2 Voltage monitor 2
Differences in Relo	Software Interrupt Number	8	တ	15	19	20	20	51

## 4. Notes

Each product has different oscillation circuit constants of XIN-XOUT, XCIN-XCOUT. Therefore, contact an oscillator manufacturer when selecting an oscillator and oscillation circuit constants so that a stable operation clock can be obtained on the user system and conditions for mass-production. Be careful especially when the voltage and temperature range is wide. The wiring pattern of the feedback resistor, damping resistor, and the load capacity should be considered in advance when designing a circuit.

In addition, although compatibility in characteristics is fully considered when designing each device, actual values such as operating margin, A/D conversion accuracy, noise immunity, noise radiation may be different within the range of electrical characteristics due to different manufacturing processes. Therefore, perform sufficient system evaluations for each individual product before starting mass production.

## 5. Reference Documents

R8C/35A Group User's Manual: Hardware Rev.0.40
R8C/35C Group User's Manual: Hardware Rev.1.00
R8C/35D Group User's Manual: Hardware Rev.1.00
R8C/35M Group User's Manual: Hardware Rev.0.10

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	R8C/35A, R8C/35C, R8C/35D, R8C/35M Groups
Revision History	Differences between R8C/35A, R8C/35C, R8C/35D, and
	R8C/35M Groups

Rev.	Date		Description
Nev.	Date	Page	Summary
1.00	June 24, 2010		First edition issued
		_	Document number changed (old number: REJ05B1375)
2.00	Jan 20, 2011	Full page	Differences of R8C/35M Group added
2.00	20, 20 1 1	3	Table 3.1 Differeneces of A/D converter sampling time and A/D conversion execution time added
		Full page	Descriptions in tables reviewed and revised
2.01	Feb. 3, 2011	2	Table 3.1 Power Control revised
		5	Table 3.4 CM3 revised

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The following usage notes are applicable to all MPU/MCU products from Renesas. For detailed usage notes on the products covered by this manual, refer to the relevant sections of the manual. If the descriptions under General Precautions in the Handling of MPU/MCU Products and in the body of the manual differ from each other, the description in the body of the manual takes precedence.

#### 1. Handling of Unused Pins

Handle unused pins in accord with the directions given under Handling of Unused Pins in the manual.

The input pins of CMOS products are generally in the high-impedance state. In operation with an unused pin in the open-circuit state, extra electromagnetic noise is induced in the vicinity of LSI, an associated shoot-through current flows internally, and malfunctions occur due to the false recognition of the pin state as an input signal become possible. Unused pins should be handled as described under Handling of Unused Pins in the manual.

### 2. Processing at Power-on

The state of the product is undefined at the moment when power is supplied.

— The states of internal circuits in the LSI are indeterminate and the states of register settings and pins are undefined at the moment when power is supplied.
In a finished product where the reset signal is applied to the external reset pin, the states of register settings and pins are undefined at the moment when power is supplied.

In a finished product where the reset signal is applied to the external reset pin, the states of pins are not guaranteed from the moment when power is supplied until the reset process is completed.

In a similar way, the states of pins in a product that is reset by an on-chip power-on reset function are not guaranteed from the moment when power is supplied until the power reaches the level at which resetting has been specified.

### 3. Prohibition of Access to Reserved Addresses

Access to reserved addresses is prohibited.

 The reserved addresses are provided for the possible future expansion of functions. Do not access these addresses; the correct operation of LSI is not guaranteed if they are accessed.

### 4. Clock Signals

After applying a reset, only release the reset line after the operating clock signal has become stable. When switching the clock signal during program execution, wait until the target clock signal has stabilized.

— When the clock signal is generated with an external resonator (or from an external oscillator) during a reset, ensure that the reset line is only released after full stabilization of the clock signal. Moreover, when switching to a clock signal produced with an external resonator (or by an external oscillator) while program execution is in progress, wait until the target clock signal is stable.

## 5. Differences between Products

Before changing from one product to another, i.e. to one with a different part number, confirm that the change will not lead to problems.

— The characteristics of MPU/MCU in the same group but having different part numbers may differ because of the differences in internal memory capacity and layout pattern. When changing to products of different part numbers, implement a system-evaluation test for each of the products.

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