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## Section 1 Overview of Programming for Multi-core

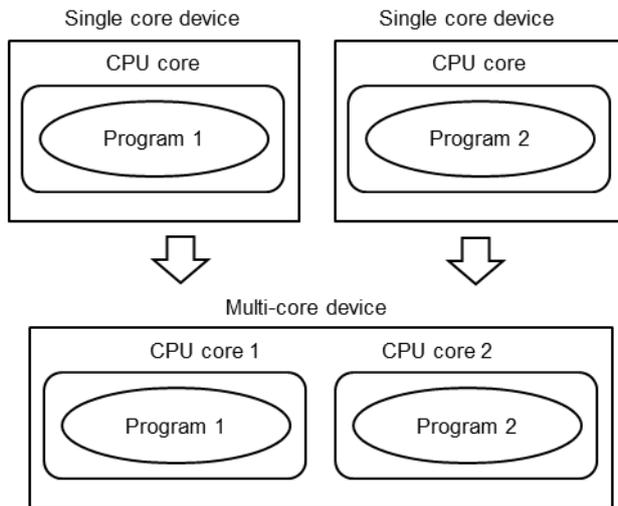
This chapter describes the overview of programming for a multi-core device.

### 1.1 Programming Models

There are three models that are used as programming models for a multi-core device: simple integrated model, distributed functional model, and distributed load model.

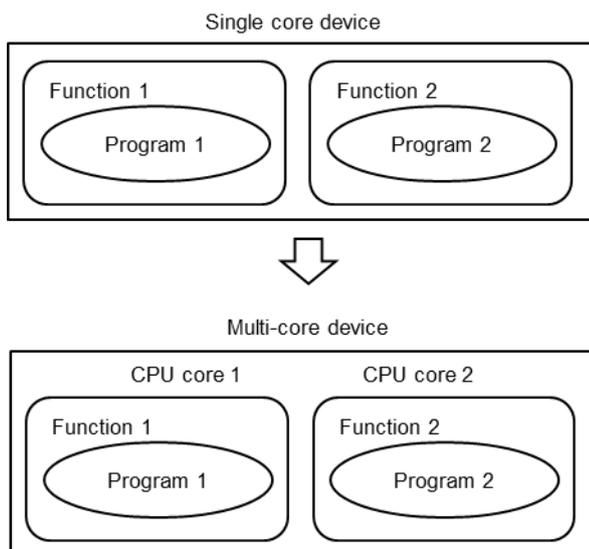
#### Simple integrated model

In this programming model, two programs that were being executed by separate single core devices are to be executed by separate cores in a multi-core device. Basically, the two programs are executed independently in each core without interfering with each other.



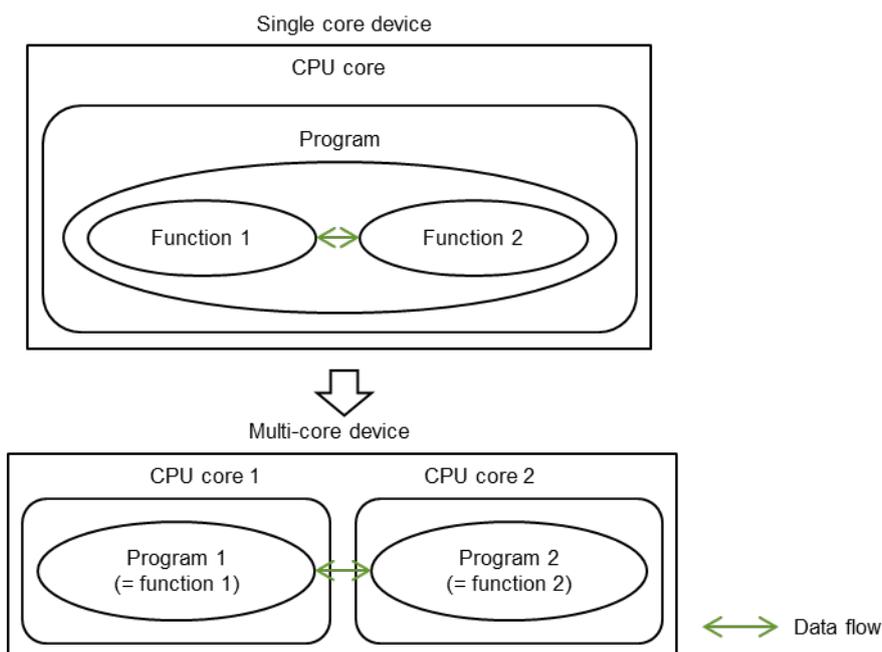
#### Distributed functional model

In this programming model, two independent functions which were in a single program are to be executed by separate cores in a multi-core device.



## Distributed load model

In this programming model, two highly-independent and dividable functions which were in a single program are to be divided into two programs, and these two programs are to be executed by separate cores in a multi-core device. If data needs to be passed between the two programs, data is passed through inter-process communication.



## 1.2 Program Configuration Examples

A programming configuration example and execution processing are described separately for each programming model.

A file configuration such as shown below is assumed when there are two cores.

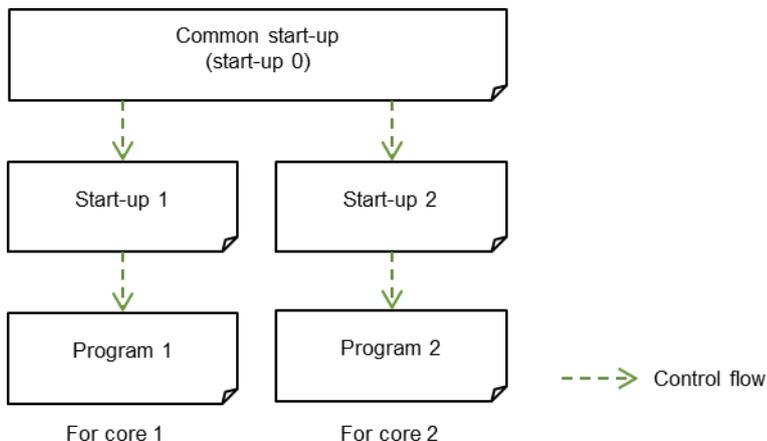
Program and start-up process executed by core 1 -> Program 1 and start-up 1

Program and start-up process executed by core 2 -> Program 2 and start-up 2

Common start-up process starting from a multi-core reset up to a branch to the start-up process for each core  
-> Start-up 0

## Configuration example of simple integrated model or distributed functional model

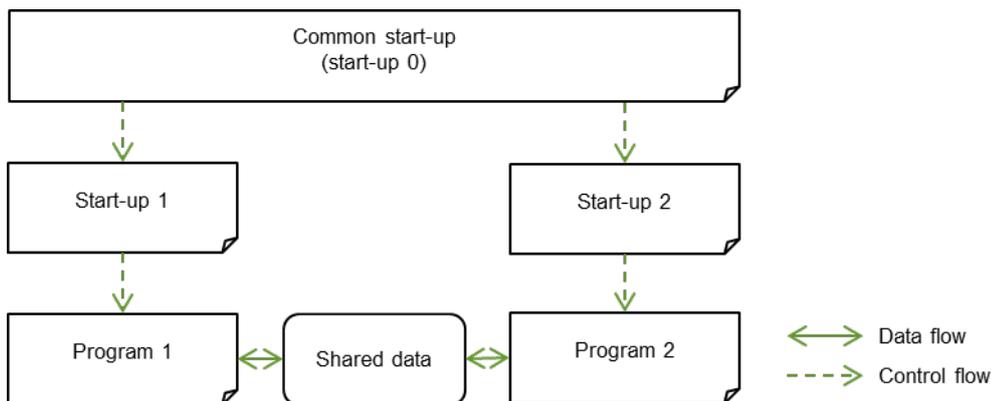
Start-up 0 initializes the resources of the entire multi-core device and then calls start-up 1 and start-up 2. Start-up 1 and start-up 2 initialize the resources of their respective core and then respectively call program 1 and program 2.



## Configuration example of distributed load model

In addition to a file of the distributed functional model, a shared data file defining the data to be shared is prepared. The shared data can also be defined in program 1 or program 2.

Start-up 0 initializes the resources of the entire multi-core device and then calls start-up 1 and start-up 2. Start-up 1 and start-up 2 initialize the resources of their respective core and then respectively call program 1 and program 2.



The shared data can be accessed from program 1 or program 2.

If the shared data is only read-only data, no particular process is required to read data from program 1 or program 2. On the other hand, if the shared data can also be used for writing, synchronized control or exclusive control needs to be performed when data is read from or written to program 1 or program 2. This is to prevent the shared data from being simultaneously accessed from both programs. Care is required because the execution result may be unintended if the data to be read or written is accessed from both programs at the same time.

## Sharing of functions in each programming model:

Functions can be shared in either of the above two programming models.

Prepare the shared function file defining the shared functions that are called from program 1 and program 2. The shared function file can also be included in program 1 or program 2. This enables the code size of the entire multi-core device to be reduced.



If the shared function is a re-entrant function, no particular process is required to call the function from program 1 or program 2. On the other hand, if the shared function is not a re-entrant function, synchronized control or exclusive control needs to be performed when the function is called from program 1 or program 2. This is to prevent the shared function from being simultaneously called from both programs. Care is required because the execution result may be unintended if a non-reentrant function is called from both programs at the same time. When a global variable is referenced from a shared function, the absolute address needs to be used for reference.

## Section 2 Correspondence Relationship with Tutorial

"Tutorial for RH850 Multi-core Environment (Build)" gives specific examples of terms in this document. The correspondence relationship between terms in this document and "Tutorial for RH850 Multi-core Environment (Build)" is shown in "Table 1 Correspondence Relationship with Tutorial for RH850 Multi-core Environment".

**Table 1** Correspondence Relationship with Tutorial for RH850 Multi-core Environment

<b>Overview of Programming for RH850 Multi-core</b>	<b>Tutorial for RH850 Multi-core Environment (Build)</b>
Common start-up	2.2.1 Start-up routine for boot loader
Start-up 1 or start-up 2	3.2.1 Start-up routine for application
Program 1 or program 2	Section 3 Application Project
Shared data	3.4 Sharing the Variables
Shared function	3.5 Sharing the Functions

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