

## Real-Time OS M3T-MR30/4 Supports an Additional MCU Series

The real-time OS for the M16C/60, M16C/30, M16C/20, M16C/10, and M16C/Tiny MCU series--M3T-MR30/4 V.4.00 Release 00--has added the R8C/Tiny series of MCUs to its support line.

### 1. MCUs Added to the Support Line

The members of the R8C/Tiny series

### 2. Procedures for Supporting the R8C/Tiny Series

#### 2.1 Settings of the GUI Configurator and the Configuration Files

(1) In the definition of the system clock, set "timer" to "OTHER".

Example:

```
clock{  
    .....  
    timer = OTHER;  
    .....  
};
```

(2) In the definitions of the interrupt handlers, define the timer interrupts as those handled by the system-clock interrupt handler, where the name of the system-clock interrupt handler must be "\_\_SYS\_STMR\_INH".

Example:

This is an example of defining the timer RA interrupt in the R8C/Tiny series as the one handled by the system-clock interrupt handler.

```
interrupt_vector[22]{  
    entry_address=__SYS_STMR_INH;  
    os_int=YES;  
};
```

#### 2.2 Modifications Made to the Startup Files (crt0mr.a30, start.a30)

Modify a portion of initializing the system clock in the startup files so that the user can use the timers in the R8C/Tiny series.

Example:

This is an example of calling the initializing function of the RA timer written in C.

```
; +-----+
; |   System timer interrupt setting           |
; +-----+
;   mov.b  #stmr_mod_val,stmr_mod_reg  ;set timer mode
;   mov.b  #stmr_int_IPL,stmr_int_reg  ;set timer IPL
;   mov.w  #stmr_cnt,stmr_ctr_reg      ;set interval count
;   or.b   #stmr_bit+1,stmr_start      ;system timer start
.glb _timer_ra_init
JSR.W _timer_ra_init
```

For details of the initializing function of the RA timer, see Application Note of the R8C/Tiny series.

## 2.3 Modifications Made to the Section Definition Files (c\_sec.inc, asm\_sec.inc)

Modify the address locations of the fixed vector table to meet the R8C/Tiny series.

Example :

This is an example of locating sections in the c\_sec.inc file.

In this example, modifications are made to address locations of the variable vector table according to the modifications made to those of the fixed vector table.

```
;-----
; VECTOR TABLE
;-----
.glb  __INT_VECTOR
.section  INTERRUPT_VECTOR  ;Interrupt vector table
.org    0fd00H
__INT_VECTOR:
.section  FIX_INTERRUPT_VECTOR ;Fixed Interrupt vector table
.org    0ffdch
```

## 3. Notices

### 3.1 On Disabling the Watchdog Timer

If you don't use the watchdog timer, disable it using the assembly directive command ".ofsreg".

Example:

Place the following two lines at the end of the example shown in 2.3:

```
;WDT disable  
.ofsreg 0FFH
```

### **3.2 On the Cycle of the System Clock**

The cycle of the system clock set in the configuration file (the value to which "tic\_num" has been set in the system definitions) must be the same as the cycle of interrupts generated by the initialization of the system clock by the user.

### **3.3 On Debugging Capabilities Supported by M3T-MR30/4**

The RTOS debugging capabilities (MR, MR Trace, and MR TaskPause windows) supported by M3T-MR30/4 and used in the emulator debuggers and simulator debuggers that have already been released cannot support the R8C/Tiny series.

We are making these capabilities support the R8C/Tiny series in the next release of each debuggers.

### **3.4 On Combination with High-performance Embedded Workshop 4**

#### (1) Creating Projects

In the "New Project-2/6-Select RTOS" dialog box, you must select "All Target" as "Target Type" when creating projects.

#### (2) Selecting the "-R8C" Option in the Toolchain

"-R8C" option is not selected automatically at creating projects.

You need to specify it as a command option explicitly.

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